

LECTURE 1

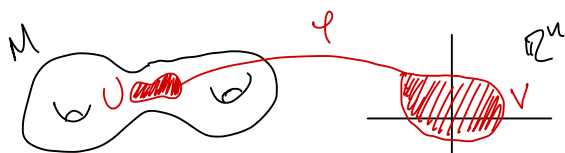
INTRODUCTION

Sep 5th, 2024

TOPOLOGICAL MANIFOLDS

Def: (Topological Mnfld) A real n -dimensional topological mfnld is a Hausdorff, 2nd countable topological space that is locally homeomorphic to $\mathbb{R}^n$.

← i.e., $\forall p \in M \exists (U, \varphi) \rightarrow \bigcup_p U \subset M \text{ open}$



$\varphi: U \rightarrow V \subset \mathbb{R}^n$
homeomorphism
(i.e., φ is continuous w/
continuous inverse)

Such (U, φ) is called a COORDINATE CHART around p b/c the "standard fcts" $x^1, \dots, x^n: \mathbb{R}^n \rightarrow \mathbb{R}$ define "coordinates".

Ex: $\emptyset, \mathbb{R}^n$

Ex: Any open subset of $\mathbb{R}^n$ or any another top. mfnld.

$\text{Mat}(n, \mathbb{R}) := \{n \times n \text{ matrices w/ real entries}\} \simeq \mathbb{R}^{n^2}$.

$\cup$

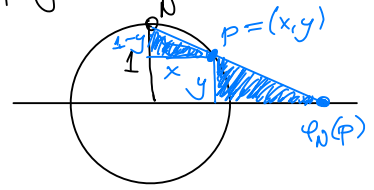
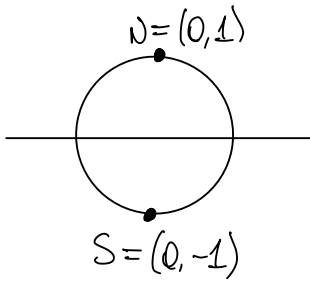
$\text{GL}(n, \mathbb{R}) = \{X \in \text{Mat}(n, \mathbb{R}) : \det X \neq 0\}$

polynomial in the entries of X
i.e., $\det^{-1}(\mathbb{R}^n \setminus \{0\})$ is open
open

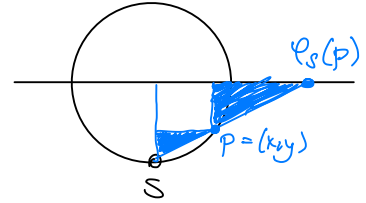
Ex: Circle $S^1 = \{(x,y) \in \mathbb{R}^2 : x^2 + y^2 = 1\} \subset \mathbb{R}^2$.

Define an atlas for S^1 via stereographic projection

$$S^1 \supset U_N := S^1 \setminus \{N\} \quad \text{open}$$



$$S^1 \supset U_S := S^1 \setminus \{S\} \quad \text{open}$$



Homeomorphisms: (Stereographic projection)

$$\begin{cases} \varphi_N : U_N \rightarrow \mathbb{R}, & \varphi_N(x, y) = \frac{x}{1-y} \\ \varphi_S : U_S \rightarrow \mathbb{R}, & \varphi_S(x, y) = \frac{x}{1+y} \end{cases}$$

Ex: Cartesian products: If M^n, N^m are mfd, then $M \times N$ (in the product top.) is a mfd as well.

$\{(U_\alpha, \varphi_\alpha)\} \rightarrow$ Atlas for M

$\{(V_\beta, \psi_\beta)\} \rightarrow$ Atlas for N

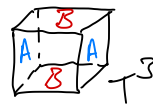
$$\Rightarrow \{(U_\alpha \times V_\beta, \varphi_\alpha \times \psi_\beta)\}$$

$$(\varphi_\alpha \times \psi_\beta)(p, q) = (\varphi_\alpha(p), \psi_\beta(q))$$

Result: mfd of dim $n+m$

$$\mathbb{R}^n \times \mathbb{R}^m$$

Ex: $T^n := \underbrace{S^1 \times \dots \times S^1}_n \text{ times}$



Ex: $S^n = \{x \in \mathbb{R}^{n+1} : \|x\|^2 = 1\}$.

$$\sum_{i=0}^n x_i^2 = \|x\|^2$$

Atlas: $\{(U_N, \varphi_N), (U_S, \varphi_S)\}$

$$N := (1, 0, \dots, 0)$$

$$S := (-1, 0, \dots, 0)$$

$$U_N := S^n \setminus \{N\}$$

$$U_S := S^n \setminus \{S\}$$

$$\varphi_N: U_N \rightarrow \mathbb{R}^n$$

$$\varphi_S: U_S \rightarrow \mathbb{R}^n$$

$$\varphi_N(x) = \frac{(x^1, \dots, x^n)}{1 - x^0}$$

$$\varphi_S(x) = \frac{(x^1, \dots, x^n)}{1 + x^0}$$

stereographic
proj.

Obs: If M^n, N^n are n -manifolds then $M \sqcup N$ is an n -manifold.

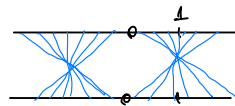
Ex: (Why Hausdorff?) Consider

$$\mathbb{R} =: \mathbb{R}_1 \supset \mathbb{R}_1^* := \mathbb{R}_1 \setminus \{0\}$$

$$\mathbb{R} =: \mathbb{R}_2 \supset \mathbb{R}_2^* := \mathbb{R}_2 \setminus \{0\}$$

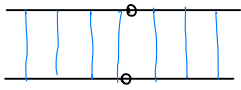
Glue $\mathbb{R}_1$ to $\mathbb{R}_2$ along gluing region $\mathbb{R}_1^*, \mathbb{R}_2^*$. To do this, we need a homeomorphism $\mathbb{R}_1^* \rightarrow \mathbb{R}_2^*$.

Option 1: use $\mathbb{R}_1^* \xrightarrow{\varphi} \mathbb{R}_2^*$
 $t \mapsto t^{-1}$



Then $\mathbb{R}_1 \sqcup \mathbb{R}_2 / \mathbb{R}^* \ni x \sim \varphi(x) \in \mathbb{R}_2^* = S^1$.

Option 2: Use $\mathbb{R}_1^* \xrightarrow{\varphi} \mathbb{R}_2^*$. Then $\mathbb{R}_1 \sqcup \mathbb{R}_2 / \underset{\substack{\sim \\ \mathbb{R}_1^*}}{x} \sim \underset{\substack{\sim \\ \mathbb{R}_2^*}}{\varphi(x)} = \mathbb{B}$
 $t \mapsto t$

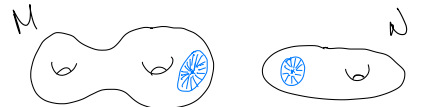


Line with 2 origins

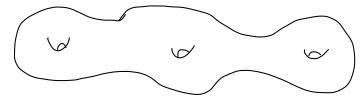
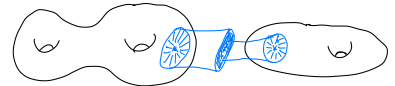
PROBLEM: Is loc. homom. to Euclidean space
 but has this exotic behavior that can be problematic.

WARNING: When building mfd's via gluing, really need to pay
 attention to whether the Hausdorff condition is satisfied (b/c
 it is not inherited by quotient topology) !

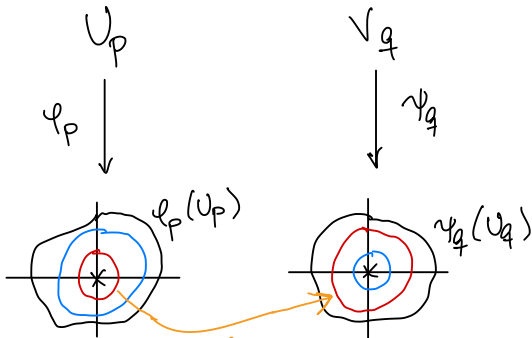
CONNECTED SUM: M^n, N^n mfd's
 $\underset{p}{\cup} \quad \underset{q}{\cup}$



Charts: (U_p, φ_p) and (V_q, ψ_q)
 s.t. $\varphi_p(p) = 0$ and $\psi_q(q) = 0$.



$M \# N$



Choose balls of radius 2ϵ and
 annulus of radius ϵ .

Define

$$\phi(x) := \frac{2\epsilon^2}{\|x\|^2} x$$

$$M \# N := \frac{(M \setminus \overline{\varphi^{-1}(B_\epsilon)}) \sqcup (N \setminus \overline{\psi^{-1}(B_\epsilon)})}{x \sim \varphi^{-1}(\phi(\psi(x))) \quad \forall x \in \varphi^{-1}(B_{2\epsilon})}$$

LECTURE 2

PROJECTIVE SPACES, ETC.

Sep 6th, 2024

REMARK: Topological mfd's are objects in the category TOP . The morphisms $X \rightarrow Y$ in TOP are continuous maps.

Isomorphisms in TOP :

$$X \begin{array}{c} \xrightarrow{f} \\ \xleftarrow{g} \end{array} Y \quad \begin{array}{l} f, g \text{ are morphisms st. } fg = \mathbb{1}_Y \text{ and } gf = \mathbb{1}_X. \\ f, g \text{ are called } \underline{\text{homeomorphisms}}. \end{array}$$

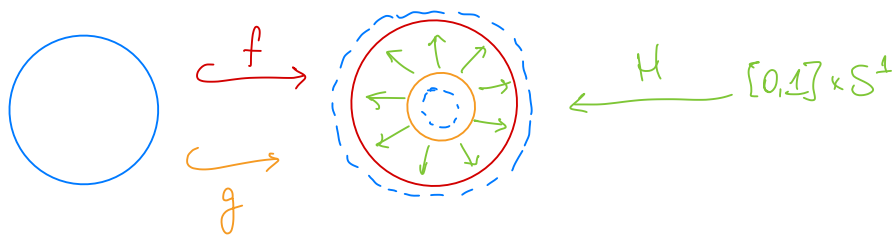
(actually, TOP is a subcategory of topological spaces)

Feature of top. spaces: In top. spaces, two continuous maps may be related (equiv. relation) by a homotopy; i.e.:

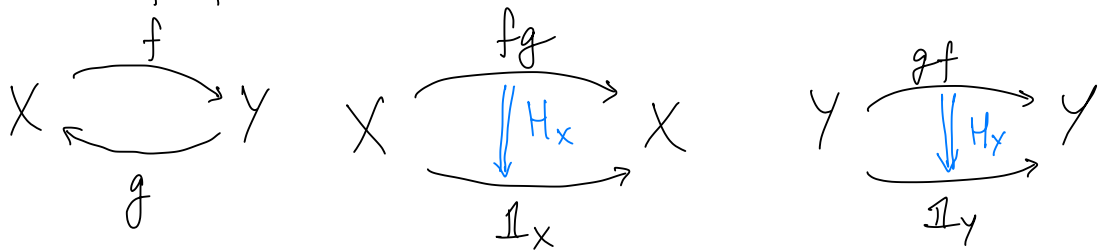
$$X \begin{array}{c} \xrightarrow{f} \\ \xrightarrow{\quad} \end{array} Y \quad \begin{array}{l} f, g \text{ are } \underline{\text{homotopic}} \text{ if we can continuously} \\ \text{interpolate them; i.e.:} \end{array}$$

$$\begin{array}{l} \exists H: [0,1] \times X \longrightarrow Y \quad \text{continuous st. } H_0(x) = f(x) \\ (t, x) \longmapsto H_t(x) \quad \quad \quad H_1(x) = g(x) \end{array}$$

e.g.: circle embedded in an annulus



Def: Top. spaces X, Y are HOMOTOPY EQUIVALENT when:



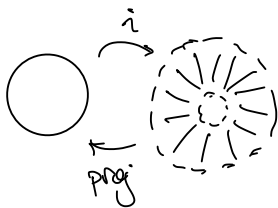
$$H_X: [0,1] \times X \rightarrow X$$

$$H_Y: [0,1] \times Y \rightarrow Y$$

i.e., fg is homotopic to 1_X and gf is homotopic to 1_Y (not equal to identity but very close to it)

i.e., f and g are inverses to each other up to homotopy.

Ex:



are homotopy equivalent but not homeomorphic.

(Top. Poincaré)

CONJECTURE: Is it possible for an n -dim top. manifold X to be

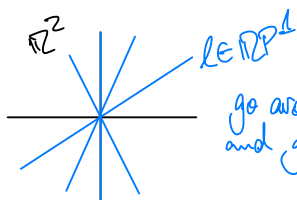
- Homotopy equiv. to S^n
- not homeo. to it?

A: No.

- $n \geq 5$ Smale 60-70
- $n = 4$ Freedman 80-90
- $n = 3$ Hamilton-Persson 00s
- $n = 1, 2$ conseq. of classification then

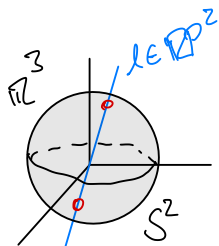
* PROJECTIVE SPACES :

over $\mathbb{R}$: $\mathbb{RP}^n = \text{space of lines through } 0 \text{ in } \mathbb{R}^{n+1}$



go around 180°
and go back to l

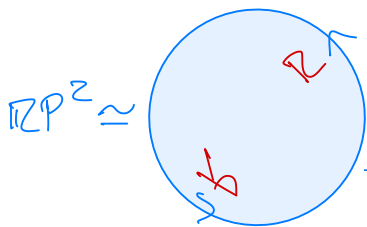
$$\leadsto \mathbb{RP}^1 = [0, \pi] / \sim \simeq S^1$$



$\mathbb{RP}^2 \not\simeq S^2$ (the antipodal pt. in the sphere produces the same line through 0)

$$\mathbb{RP}^2 \simeq S^2 / x \sim -x$$

$\leadsto$ Another way of doing this is just considering the upper hemisphere of S^2 . Then the problematic pts. are on the bdy of the hemisphere



$$\mathbb{RP}^2 \simeq$$

Identify the antipodal pts on the bdy of this disc (which represents the upper hemisphere)

Obs: because we never get the "same $\mathbb{R}$ " going around, we say $\mathbb{RP}^2$ is non-orientable.

Def: ($\mathbb{RP}^n$) Start with $X = \mathbb{R}^{n+1} \setminus \{0\}$. Define an equivalence relation

$$X \ni x \sim y \in X \iff \exists \lambda \in \mathbb{R} \text{ st. } \lambda x = y \quad (\text{i.e., pts. are equiv iff they are colinear})$$

Then, define

$$\mathbb{RP}^n := X / \sim \text{ with the quotient topology.}$$

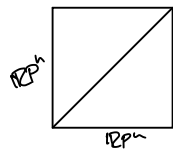
Claim: $\mathbb{RP}^n$ is an n -dim. mfd.

Pf: Let $\pi: X = \mathbb{R}^{n+1} \setminus \{0\} \longrightarrow \mathbb{RP}^n$ be the projection map.
Want to show that π is OPEN (i.e., $\underset{\text{open}}{U} \subset X \Rightarrow \pi(U) \subset \underset{\text{open}}{\mathbb{RP}^n}$),
This is true b/c

$\underset{\text{open}}{U} \subset X \Rightarrow \pi^{-1}(\pi(U))$ is open. Why? B/c $\pi^{-1}(\pi(U)) = \bigcup_{\lambda \in \mathbb{R}} \lambda U$ open

Thus: $\mathbb{RP}^n$ is 2nd countable.

NTS: $\mathbb{RP}^n$ is Hausdorff. $\Leftrightarrow$ Diagonal in $\mathbb{RP}^n \times \mathbb{RP}^n$ is closed
 $\Delta_{\mathbb{RP}^n} := \{(x, x) : x \in \mathbb{RP}^n\}$



But since we have $\pi: X \times X \longrightarrow \mathbb{RP}^n \times \mathbb{RP}^n$

$$\{(x, y) \in X \times X : x \sim y\} =: \bigcup_{\sim} \Gamma_{\sim} = \text{preimage of } \Delta_{\mathbb{RP}^n}$$

to show $\mathbb{RP}^n \times \mathbb{RP}^n \setminus \Delta_{\mathbb{RP}^n}$ is open, we can just use that π is open and that

$$\mathbb{RP}^n \times \mathbb{RP}^n \setminus \Delta_{\mathbb{RP}^n} = (\pi \times \pi) \left(X \times X \setminus \bigcup_{\sim} \Gamma_{\sim} \right)$$

So,

$\mathbb{RP}^n$ is Hausdorff $\Leftrightarrow \bigcup_{\sim} \Gamma_{\sim} \subset X \times X$ is closed.

Has to show $\bigcup_{\sim} \Gamma_{\sim}$ is closed? Express $\bigcup_{\sim} \Gamma_{\sim}$ as the zero set/preimage of a pt. of a continuous map.

Have $\mathbb{R}^{n+1} \setminus \{0\} \ni x \sim y \in \mathbb{R}^{n+1} \setminus \{0\}$. Need to define a map that detects whether x and y

$$(x^i)_{i=0}^n \quad (y^i)_{i=0}^n$$

are lin. dependent or not.

$$\mathbb{P}_i = M^{-1}(0)$$

where $M(x, y) = x \wedge y$.

Atlas for $\mathbb{RP}^n$: $U_i := \pi(\tilde{U}_i)$, where

$$\tilde{U}_i := \{(x^0, \dots, x^n) \in \mathbb{R}^{n+1} \setminus \{0\} : x_i \neq 0\}$$

$\leftarrow n+1$ hyperplane complements

$\leftarrow$ deleting the i -th hyperplane.

$$\varphi_i: U_i \rightarrow \mathbb{R}^n$$

$$[(x^0, \dots, x^n)] \mapsto \left(\frac{x^0}{x^i}, \frac{x^1}{x^i}, \dots, \frac{x^{i-1}}{x^i}, \dots, \frac{x^{i+1}}{x^i}, \dots, \frac{x^n}{x^i} \right)$$

• φ_i well-defined ✓

• φ_i continuous ✓

• φ_i invertible ✓ w/ inverse $(y^1, \dots, y^n) \xrightarrow[\text{and clearly continuous}]{\substack{\text{is the} \\ \text{inverse} \\ \text{of } \varphi_i}} [(y^1, \dots, \overset{\text{etc}}{\underset{\downarrow}{1}}, \dots, y^n)]$

Upshot: $\{(U_0, \varphi_0), \dots, (U_n, \varphi_n)\}$ is an atlas for $\mathbb{RP}^n$ since

$$\mathbb{RP}^n = \bigcup_{i=0}^n U_i$$

Same for $\mathbb{CP}^n$... but complex

LECTURE 3

FLAGS & GRASSMAN

Sep 12th, 2024

S^n , $\mathbb{R}P^n$, $\mathbb{C}P^n$, $Gr_k(V) = \text{space of } k\text{-dim subspaces of } n\text{-dim vec. space}$
 $Gr_1(\mathbb{R}^{n+1})$ $Gr_1(\mathbb{C}^{n+1})$

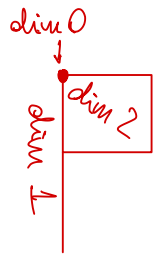
$\cap$

"FLAG MANIFOLDS" $\rightarrow Fl_{\mathbb{R}}(n) = \text{space of "full" flags in } \mathbb{R}^n$

$\cup$

$$\{ \{0\} \subset V_1 \subset V_2 \subset \dots \subset V_{n-1} \subset \mathbb{R}^n \}$$

$\dim V_i = i$



Ex: $Fl(3) = \{ \{0\} \subset V_1 \subset V_2 \subset \mathbb{R}^3 \}$.

forget V_1 / π_1

forget V_2

$$Gr_2(\mathbb{R}^3) \simeq \mathbb{R}P^2$$

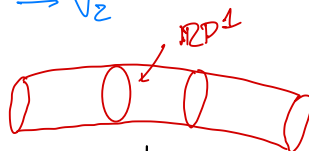
$$\mathbb{R}P^2$$

inclusion $V_2 \xrightarrow{2} \mathbb{R}^3$

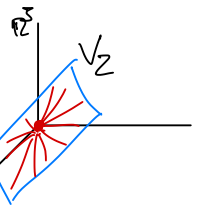
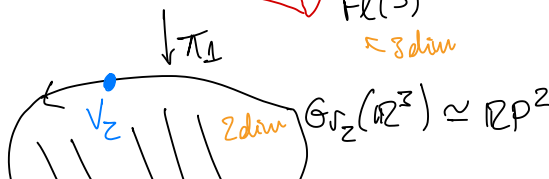
Fix $V_2 \subset \mathbb{R}^3$ and consider $\pi_1^{-1}(V_2)$

Annihilator $(V_2) = K_{\perp} \rightarrow (\mathbb{R}^3)^* \xrightarrow{2^*} V_2^*$
 $\underbrace{\quad}_{\text{kernel of } 2^*}$

Have: $\pi_1^{-1}(V_2) = \{ V_1 \text{ 1-dim subspace of } V_2 \}$
 $\simeq \mathbb{R}P^1$



$Fl(3)$
 $\simeq 3\text{dim}$





$\Rightarrow Fl(3)$ is a bundle of $\mathbb{RP}^1$ over base $\mathbb{RP}^2$ with π_1 as the bundle projection.

Ex: (FIBER BUNDLES) Let F be a top. space (the FIBER). A fiber bundle with fiber F is (E, π, B) where

- E (TOTAL SPACE) and B (BASE SPACE) are top. spaces
- $\pi: E \rightarrow B$ continuous surjective (BUNDLE PROJECTION MAP)

SUCH THAT: $\forall p \in B \exists$ a neighborhood $U \ni p$ and a homeo.

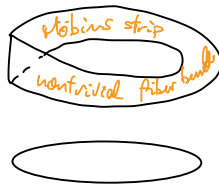
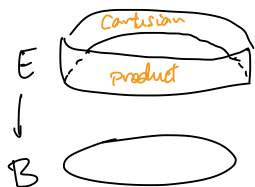
$$\Phi: \pi^{-1}(U) \longrightarrow U \times F \quad (\text{LOCAL TRIVIALITY})$$

π $\searrow$ $\downarrow \pi_1$
 U
 that commutes with the projections.

i.e., locally, the bundle is a Cartesian product. We just don't want it to be globally trivial...

claim: If F, B are top. spaces then so is E .

Rmk: There are many fiber bundles with the same base & fiber



$$F = (0, 1)$$

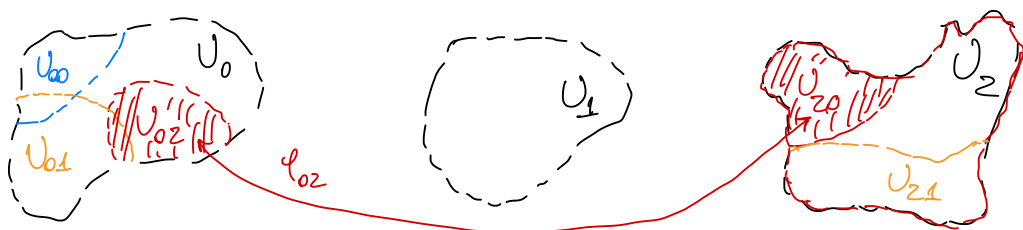
GLUING CONSTRUCTION OF MANIFOLDS

Begin with: a countable collection of open sets $\mathcal{A} = \{U_i\}_{i \in I}$

Idea: Quotient $\bigsqcup_{i \in I} U_i$ by an equiv. relation to get

$$M = \bigsqcup_{i \in I} U_i / \sim$$

Gluing: $\forall i$ choose finitely many opens $U_{ij} \subset U_i$



and gluing maps $\varphi_{ij}: U_{ij} \xrightarrow{\sim} U_{ji}$ (homeos.).

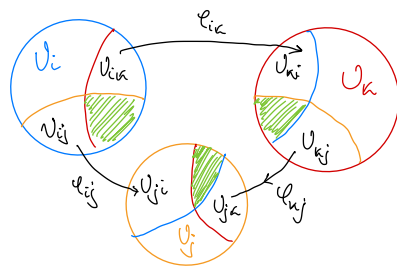
Gluing maps define an equivalence relation iff:

(i) $\varphi_{ij} \varphi_{ji} = \text{id}_{U_{ji}}$ $\varphi_{ji} \varphi_{ij} = \text{id}_{U_{ij}}$

(reflexivity)

(ii) $\varphi_{ij}(U_{ij} \cap U_{ik}) = U_{ji} \cap U_{jk} \quad \forall k$

(transitivity)



$$\varphi_{ki} \Big|_{U_{ki} \cap U_{kj}} \circ \varphi_{jk} \Big|_{U_{ji} \cap U_{jk}} \circ \varphi_{ij} \Big|_{U_{ik} \cap U_{ij}} = \text{id}_{U_{ij} \cap U_{jk}}$$

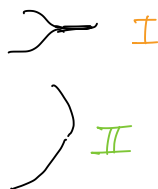
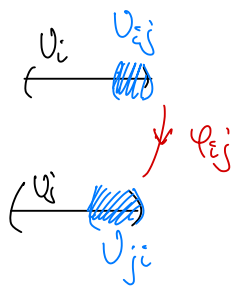
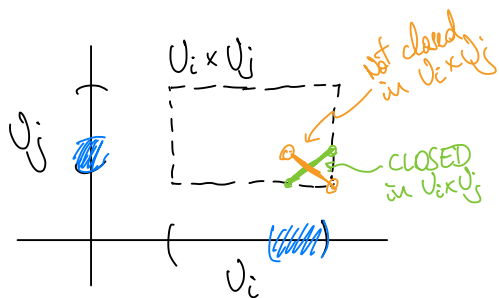
This defines an equiv. relation on $\bigsqcup_{i \in I} U_i$

$$\Rightarrow M = \bigsqcup_{i \in I} U_i / U_i \ni x \sim \varphi_{ij}(x) \in U_j$$

- top space
- 2nd countable
- locally homeo to $\mathbb{R}^n$

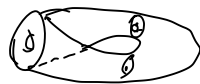
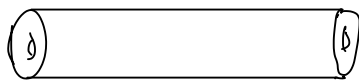
& Hausdorff under an additional assumption:

(iii) Graph of $\varphi_{ij} = \{(x, \varphi_{ij}(x)) : x \in U_{ij}\} \subset U_{ij} \times U_j$
needs to be CLOSED in $U_i \times U_j$.



Ex: (MAPPING TORUS) M top. mfd and $\phi: M \rightarrow \text{Home}$

First: $M \times \mathbb{R}$



$$\mathbb{Z} \ni t \sim t+1 \xrightarrow{\pi}$$

$$S^1 = \mathbb{R}/\sim$$

Quotient: $M_\phi := M \times \mathbb{R} / \sim$, where $(x, t) \sim (\phi(k), t+1)$

Upshot: The resulting mapping torus M_ϕ is a fiber bundle over S^1 with fiber M .

LECTURE 4

DIFFERENTIAL STRUCTURES

Sep 13th, 2024

We say $f: U \subset V \rightarrow W$, V, W finite dim vector spaces, is differentiable at $p \in U$ if there exists a linear map

$Df(p): V \rightarrow W$ that approximates f at p :

$$\lim_{\substack{x \rightarrow 0 \\ x \neq 0}} \frac{|f(p+x) - f(p) - Df(p)(x)|}{|x|} = 0.$$

$Df(p)$ uniquely characterized by this limit.

$$Df(p) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} \Big|_p & \cdots & \frac{\partial f_1}{\partial x_n} \Big|_p \\ \vdots & & \\ \frac{\partial f_m}{\partial x_1} \Big|_p & \cdots & \frac{\partial f_m}{\partial x_n} \Big|_p \end{pmatrix};$$

Def: f is continuously differentiable if

$$Df: U \rightarrow \text{Hom}(V, W)$$

is continuous. In this case, $f \in C^1(U, W)$.

Note: $C^\infty(U, W) := \bigcap_k C^k(U, W)$

Def: A smooth manifold is a topological manifold equipped with an equivalence class of smooth atlases.

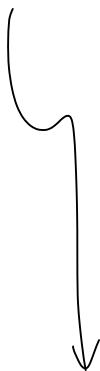
Def: An atlas $\mathcal{A} = \{(U_i, \varphi_i)\}$ for a topological manifold is smooth when all transition functions

$$\varphi_j \circ \varphi_i^{-1} \big|_{\varphi_i(U_{ij})} : \varphi_i(U_{ij}) \longrightarrow \varphi_j(U_{ij})$$

are smooth maps; i.e., lie in $C^\infty(\varphi_i(U_{ij}), \mathbb{R}^n)$.

Two atlases $\mathcal{A}, \mathcal{A}'$ are equivalent if $\mathcal{A} \cup \mathcal{A}'$ is itself a smooth atlas.

Remark: these transition maps only need to be smooth on an open subset $\varphi_i(U_i \cap U_j) \subset \mathbb{R}^n$ (not necessarily the whole $\mathbb{R}^n$).



LECTURE 5

Sep 19th, 2024

Category: collection of objects $\mathcal{C}$ and arrows A . There are two natural maps source and target telling us what is the beginning and end of each arrow: $A \xleftarrow{s} \mathcal{C} \xrightarrow{t} A$.

Also, there must be an identity 1_X : $X \xrightarrow{\quad} 1_X$.

Plus, an associative composition of arrows.

If X, Y are objects, define

$A \ni \text{Hom}_\mathcal{C}(X, Y) = \text{morphisms (arrows) from } X \text{ to } Y$.

Associative composition: $\text{Hom}(X, Y) \times \text{Hom}(Y, Z) \rightarrow \text{Hom}(X, Z)$.

$$X \xrightarrow{f} Y \xrightarrow{g} Z \xrightarrow{h} W$$
$$(h \circ g) \circ f = h \circ (g \circ f)$$

Ex: (i) $\mathcal{C} = \text{sets}$, $A = \text{maps of sets}$

(ii) $\mathcal{C} = \text{groups}$, $A = \text{group homomorphisms}$

(iii) $\mathcal{C} = \text{vec. space over } F$, $A = \text{linear maps}$

(iv) $\mathcal{C} = \text{top. spaces}$, $A = \text{continuous maps}$

* MORPHISMS BETWEEN C^∞ MANIFOLDS: If M, N are C^∞ mfd's, a map $f: M \rightarrow N$ is SMOOTH when it is continuous and C^∞ in charts; i.e., for any charts (U, φ) and (V, ψ) on M, N in the smooth atlas, we require

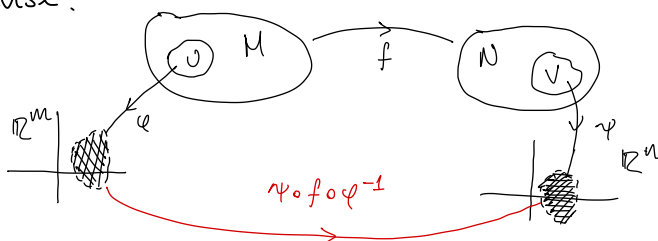
$$f_V^U := \psi \circ f \circ \varphi^{-1}: \varphi(U) \subset \mathbb{R}^m \longrightarrow \psi(V) \subset \mathbb{R}^n$$

to be C^∞ in the usual sense.

e.g.: for 1st derivative,

$$f_V^U = ((f_V^U)^1, \dots, (f_V^U)^n)$$

$$\left[\frac{\partial}{\partial x^i} (f_V^U)^j \right]_{n \times m} \text{ matrix.}$$



• The set of C^∞ maps $M \rightarrow N$ is denoted

$$\text{Hom}_{C^\infty}(M, N) = C^\infty(M, N)$$

$\Rightarrow$ identity arrow clearly

WARNING: $(\text{Id}_M)_U^V = \psi \circ \text{Id}_M \circ \varphi^{-1}$ need not be $\text{Id}_{\mathbb{R}^n}$. It's only going to look like $\text{Id}_{\mathbb{R}^n}$ if we use $(\text{Id}_M)_U^U$.

• Associative composition: we already have a continuous associative composition inherited from the topological aspect of C^∞ -mfd's. We only need to check that this composition is smooth:

Prop: If $L \xrightarrow{g} M$ and $M \xrightarrow{f} N$ are C^∞ maps, then $f \circ g$ is also C^∞ .

Pf: Check on the charts: $(f \circ g)_\# = \psi_\# (f \circ g) \circ \varphi^{-1} = \underbrace{(\psi_\# \circ f_\# \circ \chi^{-1})}_{C^\infty \text{ by assumption}} \circ \underbrace{(\chi_\# \circ g_\# \circ \varphi^{-1})}_{C^\infty}$

Composition of C^∞ is C^∞ .

KEY: Chain rule for differentiation of maps $\mathbb{R}^l \rightarrow \mathbb{R}^m$ i.e.,

$$D_p(\psi \circ f \circ g \circ \varphi^{-1}) = \underbrace{D_{\chi(g(\varphi^{-1}(p)))}(\psi \circ f \circ \chi^{-1})}_{n \times m \text{ matrix}} \underbrace{D_p(\chi \circ g \circ \varphi^{-1})}_{m \times l \text{ matrix}}$$

$n \times l$ matrix

ISOMORPHISMS in C^∞ MANIFOLDS:

i.e., arrows f with inverses g

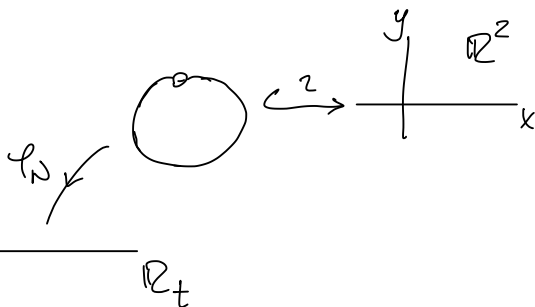
$\text{Hom}(\mathbb{R}^n, \mathbb{R}^m)$ $\text{Hom}(\mathbb{R}^m, \mathbb{R}^n)$

$f \circ g = \text{Id}_Y$
 $g \circ f = \text{Id}_X$

Such smooth maps f w/ smooth inverse g are DIFFEOMORPHISMS

Ex: $S^1 \hookrightarrow \mathbb{R}^2$ inclusion is smooth

i.e., $\varphi_N^{-1}: \mathbb{R} \rightarrow \mathbb{R}^2$ is C^∞
 $t \mapsto (x(t), y(t))$



Ex: $S^1 \times S^1 \xrightarrow{1 \times 2} \mathbb{R}^2 \times \mathbb{R}^2$ inclusion of T^2 into $\mathbb{R}^4$.
 $(z_1, z_2) \mapsto \left(\frac{1(z_1)}{\sqrt{2}}, \frac{1(z_2)}{\sqrt{2}} \right)$ so that it has length 1

$\Rightarrow S^1 \times S^1$ includes first through S^3 and then it includes into $\mathbb{R}^4$ via $S^3 \hookrightarrow \mathbb{R}^4$.

$$S^1 \times S^1 \hookrightarrow \mathbb{R}^4$$

$$\begin{array}{ccc} & S^3 & \\ \searrow & & \nearrow \\ S^1 \times S^1 & & \end{array}$$

cl: We defined a $\tau \in C^\infty(T^2, S^3)$

Pf: This involves 4 charts in domain T^2 (products of charts of S^1)
 2 charts in codomain S^3

$\Rightarrow$ Check 8 components.

Ex: (LIE GROUP) Group G is a set w/ associative multiplication
 $m: G \times G \rightarrow G$ and identity $e \in G$, and inversion $i: G \rightarrow G$
 $g \mapsto g^{-1}$

If we endow G with a C^∞ structure (i.e., an equivalence class of smooth atlases) and we require $m \in C^\infty(G \times G, G)$ and $i \in C^\infty(G, G) \implies G$ is a LIE GROUP

e.g.: $(\mathbb{R}, +, 0, i(t) = -t)$ is a Lie group $(x, y) \mapsto x+y \quad t \mapsto -t$
 $\mathbb{R}^2 \xrightarrow{C^\infty} \mathbb{R} \quad C^\infty$

$(\mathbb{R}^k, +, 0, -1)$ is a Lie group

$\mathbb{R}/\mathbb{Z} = S^1$ is a Lie group $z_1 = e^{i\theta_1}, z_2 = e^{i\theta_2} \mapsto z_1 \cdot z_2 = e^{i(\theta_1 + \theta_2)}$

- $GL(n, \mathbb{R}) \subset \mathbb{R}^{n^2}$ is a Lie group. Matrix multiplication is smooth b/c it is just a polynomial in the entries of the matrices.

- If G is a Lie group and $g \in G$ is fixed, we can define natural C^∞ maps $R_g: G \rightarrow G$ and $L_g: G \rightarrow G$
 $x \mapsto xg$ $x \mapsto gx$
 since multiplication is C^∞

Inverses: $R_{g^{-1}}$ and $L_{g^{-1}}$ (both C^∞)

$\Rightarrow R_g, L_g$ are DIFFEOMORPHISMS.

⚠ WARNING: Do not confuse DIFFEO with EQUIV. OF ATLASES.

E.g.:

$(\mathbb{R}, x)$

$\alpha(x) = x$
 $\mathbb{R}$

$\beta(x) = x^3$
 $\mathbb{R}$

α is a valid C^∞ atlas on $\mathbb{R}$

β is also a valid C^∞ atlas on $\mathbb{R}$

$\left. \begin{array}{l} \alpha, \beta \text{ represent two } C^\infty \\ \text{structures on } \mathbb{R}. \end{array} \right\}$

Is $[\alpha] = [\beta]$? No

Check: $\beta \alpha^{-1}: x \mapsto x^3$ C^∞ ✓

$$\alpha\beta^{-1}: t \mapsto t^{1/3} \text{ is not } C^\infty$$

$\Rightarrow (\mathbb{R}, \alpha)$ and $(\mathbb{R}, \beta)$ are two different C^∞ manifolds.

But this is still acceptable b/c they are ISOMORPHIC:

$$(\mathbb{R}, \alpha) \cdot \begin{array}{c} \xrightarrow{\lambda} \\ \xleftarrow{\lambda^{-1}} \end{array} \cdot (\mathbb{R}, \beta)$$

Define λ as:

$$\lambda(x) = x^{1/3} \leftarrow \text{doesn't look smooth but it is smooth with this structure and is invertible.}$$

$$\begin{array}{ccc} (\mathbb{R}, \alpha) & \xrightarrow{\lambda} & (\mathbb{R}, \beta) \\ \alpha \swarrow \searrow & & \beta \swarrow \searrow \\ \mathbb{R} & x & \mathbb{R} \quad y^3 \end{array}$$

Obs: S^7 has 28 non-isomorphic C^∞ structures lol (Kervaire-Milnor)

$\mathbb{R}^4$ has uncountably many non-iso. C^∞

$\mathbb{R}^n$ $n \neq 4$ has only 1

LECTURE 6

DERIVATIVES

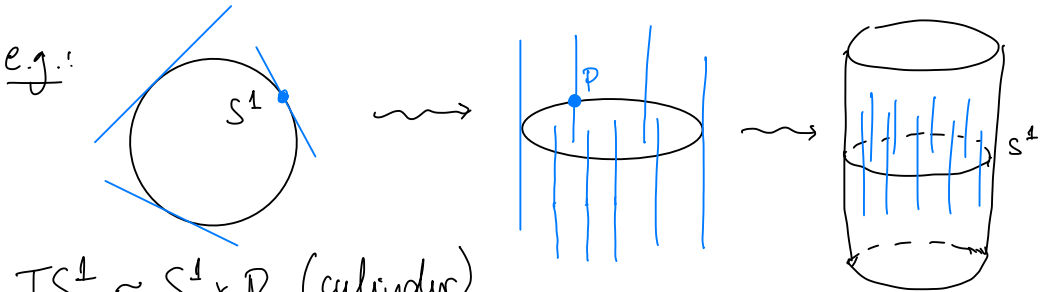
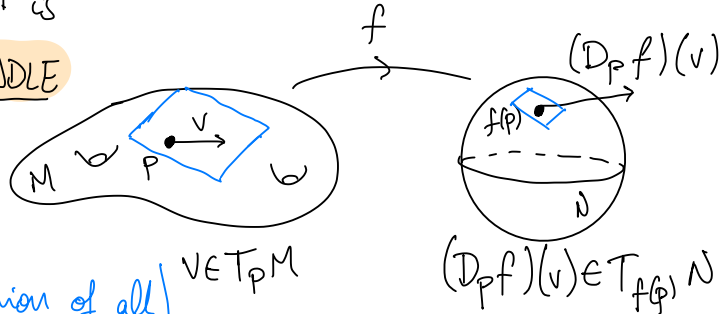
Sep 20th, 2024

To define Df , the derivative of a C^∞ map f , we need to build the space where it is defined: the **TANGENT BUNDLE**

TM

$$TM = \bigsqcup_{p \in M} T_p M$$

(union of all tangent spaces)



$$TS^1 \simeq S^1 \times \mathbb{R} \text{ (cylinder)}$$

2d manifold

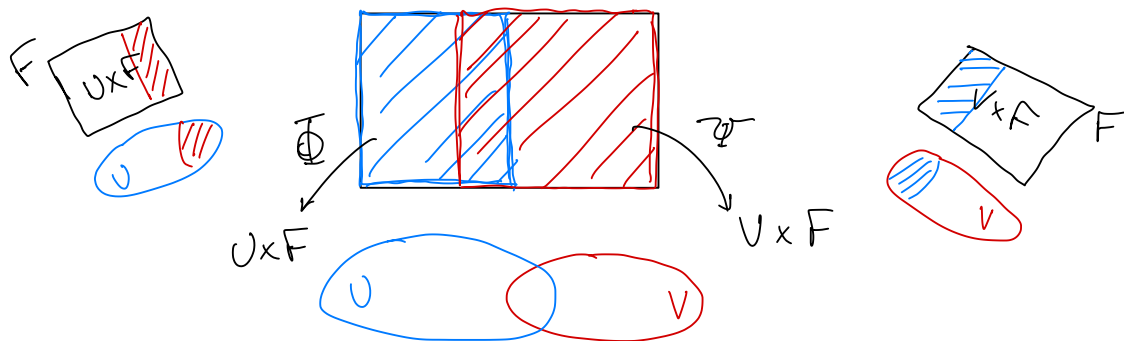
REMARK: In general $TM \neq M \times \mathbb{R}^n$ but it is a $2n$ -dim. manifold. Moreover, TM has the following structure

(Bundle Projection) $\pi: TM \rightarrow M$
 $(p, v) \mapsto p$

$TM \xrightarrow{\pi} M$ is a **FIBER BUNDLE** with fiber $\mathbb{R}^n$ (often nontrivial)

REMARK: Fiber bundles have charts

$$U, V \subset B \quad \pi^{-1}(U) \xrightarrow[\cong]{\Phi} U \times F, \quad \pi^{-1}(V) \xrightarrow[\cong]{\Psi} V \times F$$



Transition map: $\Psi \Phi^{-1}: (U \cap V) \times F \longrightarrow (U \cap V) \times F$

is a family of homeomorphisms $F \rightarrow F$ parametrized by $U \times V$.

• If $F = \mathbb{R}^n$ we can ask that $\Psi \Phi^{-1}$ respect the vec. space structure of the fiber, i.e., require

$$\Psi \Phi^{-1}: U \cap V \longrightarrow GL(n, \mathbb{R})$$

With this additional constraint, the fiber bundle is called a VECTOR BUNDLE.

GOAL: 1) Any C^∞ manifold M has a natural vector bundle

$$TM \xrightarrow{\pi} M$$

2) Any smooth map $f: M \rightarrow N$ has natural DERIVATIVE Df

$$\begin{array}{ccc}
 (TM)^{2m} & \xrightarrow{Df} & (TN)^{2n} \\
 \pi_M \downarrow & & \downarrow \pi_N \\
 M^m & \xrightarrow{f} & N^n
 \end{array}$$

which is a linear map of vector bundles.

Obs: This association $M \longmapsto TM$

$$\begin{array}{ccc}
 f \downarrow & \longmapsto & \downarrow Df = T f \\
 N & \longmapsto & TN
 \end{array}$$

↑ Tangent functor

Smooth Manifolds $\xrightarrow{T}$ Smooth Vector Bundles

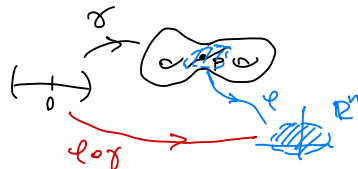
Tangent Functor

* CONSTRUCT THE TANGENT BUNDLE:

Def: $T_p M$ = equivalence classes of paths through p .

Def: Let $I \subset \mathbb{R}$ open interval containing 0. A PATH in M through p is

$$\begin{aligned}
 \gamma: I &\rightarrow M \text{ smooth} \\
 \gamma(0) &= p
 \end{aligned}$$



Def: Two paths are equivalent $\gamma_1 \sim \gamma_2$ when they have the same velocity at zero. (in any fixed chart)

i.e., in any chart (U, φ) about p

$$\left. \frac{d}{dt} \right|_{t=0} (\varphi \circ \gamma: \mathbb{I} \rightarrow \mathbb{R}^n) \in \mathbb{R}^n \quad \left. \vphantom{\frac{d}{dt}} \right\} \begin{array}{l} \text{velocity of } \gamma \\ \text{in chart } (U, \varphi) \end{array}$$

Note: This definition is independent of chart.

$\Rightarrow T_p M$ is a vector space identified with $\mathbb{R}^n$ by a chart

Changing coordinates $\varphi \circ \varphi^{-1}: \varphi(U \cap V) \rightarrow \varphi(U \cap V)$ implies

$$\underbrace{D_{\varphi(p)}(\varphi \circ \varphi^{-1})}_{\substack{\mathbb{R}^n \leftarrow \mathbb{R}^n \\ \text{Jacobian linear map}}} \underbrace{\left. \frac{d}{dt} \right|_{t=0} (\varphi \circ \gamma)}_{\substack{\text{velocity relative to } \varphi \\ \mathbb{R}^n}} = D_o(\varphi \circ \varphi^{-1} \circ \gamma) \quad \uparrow \quad \text{Chain rule for vector valued fcts.} \\ = \underbrace{\left. \frac{d}{dt} \right|_{t=0} (\varphi^{-1} \gamma)}_{\text{velocity relative to } \varphi}$$

SUMMARY: Def: Let $(U, \varphi), (V, \psi)$ smooth charts on M containing $p \in M$

$$u \in T_{\varphi(p)} \varphi(U) = \varphi(U) \times \mathbb{R}^n$$

$$v \in T_{\psi(p)} \psi(V) = \psi(V) \times \mathbb{R}^n$$

$$((U, \varphi), u) \sim ((V, \psi), v)$$

$$\text{when } D_{\varphi(p)}(\psi \circ \varphi^{-1})(u) = v$$

The space of equivalence classes is $T_p M$

Def: $TM \stackrel{\text{set}}{=} \bigsqcup_{p \in M} T_p M$ equipped with

(TM as
a set)

$$\begin{aligned} \pi: TM &\longrightarrow M \\ (p, [(U, \varphi, u)]) &\longmapsto p \end{aligned}$$

Vector Bundle

Prop: TM is equipped with a smooth (manifold) structure.

Pf: Any chart (U, φ) for M defines a bijection

(TM as
a C^∞ manifold)

$$T\varphi(U) := \varphi(U) \times \mathbb{R}^n \longrightarrow \pi^{-1}(U)$$

In this way, each chart (U, φ) endows $\pi^{-1}(U)$ with topology and chart into $\mathbb{R}^n \times \mathbb{R}^n$

$$\pi^{-1}(U) \xrightarrow{\Phi} \mathbb{R}^{2n}$$

Given another chart (V, ψ) on M , it lifts to

$$\pi^{-1}(V) \xrightarrow{\Psi} \mathbb{R}^{2n}$$

Transition:

$$\Psi \circ \Phi^{-1}: \varphi(U \cap V) \times \mathbb{R}^n \longrightarrow \psi(U \cap V) \times \mathbb{R}^n$$

$$(p, u) \longmapsto (\underbrace{\psi\varphi^{-1}(p)}_{C^\infty \text{ by assumption}}, \underbrace{D_p(\psi\varphi^{-1})(u)}_{\text{Smooth}})$$

TM inherits:

- Topology: $W \subset TM$ open $\iff W \cap \pi^{-1}(U)$ open $\forall U$ chart on M

- Hausdorff: separate $p, q \in TM$
 - if p, q lie in same chart ✓
 - if p, q don't lie in same chart, separate by charts ✓

* MORE USEFUL CONSTRUCTION OF TM ALONG W/ M:

Choose a countable atlas $\{(U_i, \varphi_i)\}_{i \in I}$ for M^n . Then

$$TM = \bigsqcup_{i \in I} (\varphi_i(U_i) \times \mathbb{R}^n) / \begin{matrix} (x, u) \sim (y, v) \\ \Leftrightarrow y = \varphi_j \circ \varphi_i^{-1}(x) \text{ \& } \\ v = D_x(\varphi_j \circ \varphi_i^{-1})(u) \end{matrix}$$

Can verify that the general gluing construction holds.

• While this depends on the atlas, if another atlas ^{smoothly equiv. to} is used, then there is a canonical diffeomorphism between the tangent bundles coming from the different atlases:

$$(\varphi_j^{-1} \circ \varphi_i^{-1})^{-1}, D(\varphi_j^{-1} \circ \varphi_i^{-1})^{-1})$$

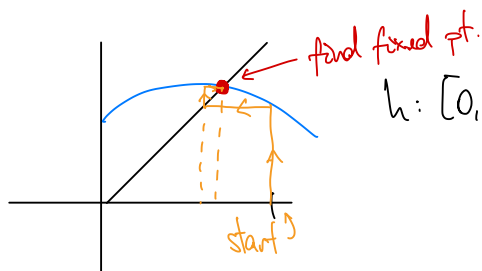
LECTURE 7

INVERSE FUNCTION & CONSTANT RANK THEOREMS

* INVERSE FUNCTION THEOREM:

Thm: (IFT) If $f: (M, p) \rightarrow (N, q)$ is a smooth map of n -manifolds such that $Df(p): T_p M \rightarrow T_q N$ is invertible, then f has a local smooth inverse. i.e., $\exists$ open neighborhoods $U \ni p$ and $V \ni q$ and a smooth $g: V \rightarrow U$ s.t. $fg = \text{Id}_V$ and $gf = \text{Id}_U$.

Pf: Step 0 (BANACH FIXED PT THM) If $h: X \rightarrow X$ is s.t. $d(h(x), h(y)) \leq \frac{1}{2} d(x, y)$ and X is complete, then $\exists!$ fixed pt.



$h: [0, 1] \rightarrow [0, 1]$ contraction map.

Setup: Reduce to case $M = \text{open in } \mathbb{R}^n$, $N = \mathbb{R}^n$, $p = q = 0$ also WLOG $Df(0) = \text{Id}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ (can replace f by $Df(0)^{-1} \circ f$).

Step 1: (DEFINE INVERSE MAP) For each y ^{close to zero as above} suff. small we want x s.t. $f(x)=y$ to be the fixed pt of a contraction map.

$$f(x) = \underbrace{x}_{\text{linear}} + \underbrace{\kappa(x)}_{\text{nonlinear part of } f} \implies x + \kappa(x) = y \text{ as a fixed pt.}$$

$$y - \kappa(x) = x$$

for any y , defined map

$$h_y: x \longmapsto y - \kappa(x)$$

fixed pt of this map would be an inverse; i.e., x s.t. $f(x)=y$.

• Check h is a contraction map:

$$Dh_y(0) = 0 \implies |Dh_y| \leq \frac{1}{2} \text{ in some ball } B_r(0).$$

$$\text{MVT} \implies |h_y(x) - h_y(x')| \leq \frac{1}{2} |x - x'| \text{ for } x, x' \in B_r(0).$$

• h_y acts on a complete vector space:

$$|h_y(x)| = |h_y(x) - h_y(0) + h_y(0)| \leq |h_y(x) - h_y(0)| + |h_y(0)|$$

$$\leq \frac{1}{2} |x| + |y|.$$

So, as long as y is chosen in $B_{\frac{r}{2}}(0)$, $\overline{B_r(0)} \xrightarrow{h_y} \overline{B_r(0)}$.

BFPT $\implies \exists!$ fixed pt. of h_y in $\overline{B_r(0)}$ for each $y \in B_{\frac{r}{2}}(0)$
so we define:

$$\begin{array}{ccc}
 g: B_{\frac{r}{2}}(0) & \longrightarrow & \overline{B_r(0)} \\
 y & \longmapsto & \text{fixed pt. of } h_y
 \end{array}$$

Inverse

Upshot: $f \circ g = \text{Id}_{B_{\frac{r}{2}}(0)} \rightarrow \text{since } h_y(g(y)) = g(y)$

$g \circ f = \text{Id}_{f^{-1}(B_{\frac{r}{2}}(0)) \cap \overline{B_r(0)}} \rightarrow \text{since fixed pt. in } \overline{B_r(0)} \text{ is unique}$

but $f^{-1}(B_{\frac{r}{2}}(0)) \cap \overline{B_r(0)}$ may not be open in M ! So, we need to shrink $B_{\frac{r}{2}}(0)$.

Step 2: (CONTINUITY OF INVERSE)

$$\begin{aligned}
 |g(y) - g(y')| &= |h_y(g(y)) - h_{y'}(g(y'))| \\
 &\leq |y - y'| + |\kappa(g(y)) - \kappa(g(y'))| \\
 &\leq |y - y'| + \frac{1}{2} |g(y) - g(y')|
 \end{aligned}$$

$$\Rightarrow |g(y) - g(y')| \leq 2|y - y'| \Rightarrow g \text{ is continuous.}$$

Step 3: (f IS LOCAL HOMEO.)

$g(0) = 0$ and continuous $\Rightarrow$ let $U \subset B_r(0)$ nbhd of zero and let $V = g^{-1}(U)$.

then $\begin{cases} f \circ g = \text{Id}_V \text{ as before} \\ g \circ f = \text{Id}_U \text{ by uniqueness of fixed pt.} \end{cases}$

Step 4: (g IS DIFFERENTIABLE AT y) If g is smooth, $Dg(y)$ must be $Df(g(y))^{-1}$ by chain rule. Now Df will be invertible on some nbhd of 0 so for this to make sense we should have chosen r small enough s.t. $Df(x)$ invertible for $x \in B_r(0)$.

Step 5: (g IS C^∞) $Dg(y) = Df(g(y))^{-1}$ since inversion is C^∞ g has as many derivatives as f does. ■

* CONSTANT RANK THEOREM

Thm: (CRT) If $f: M^m \rightarrow N^n$ is smooth and Df has constant rank k in a neighborhood of $p \in M$, then $\exists$ charts $(U, \varphi) \ni p$ and $(V, \psi) \ni f(p)$ s.t.

$$\psi \circ f \circ \varphi^{-1}: (x_1, \dots, x_m) \mapsto (x_1, \dots, x_k, 0, \dots, 0)$$

LECTURE 8

EMBEDDINGS

Oct 2nd, 2024

* REGULAR (OR EMBEDDED) SUBMANIFOLDS

Def: Let M^n be a manifold. An embedded (or regular) submanifold of codimension k is a subspace $S \subset M$ such that every $p \in S$ is contained in a chart (U, φ) of the ambient manifold M such that

$$\varphi(U \cap S) = \{x \in \varphi(U) : \underbrace{x_{n-k+1} = \dots = x_n = 0}_{\text{last } k \text{ coordinates}}\}.$$

Remark: (i) We call charts above "adapted" to S .

(ii) If the codimension $k = 1$, we say S is a hypersurface.

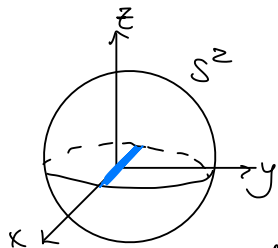
Ex: $M = S^2$, $S := \{(x, y, z) \in S^2 : y = 0\} \cong S^1$

$$U := \{z > 0\} \subset S^2, \quad \varphi(x, y, z) = (x, y)$$

$$\Rightarrow \varphi(U) = B_1(0) \text{ and } \varphi(U \cap S) = \{(x, y) \in B_1(0) : y = 0\}$$

Using $\{z < 0\}$ or x instead of z , we can cover S by adapted charts.

Alternative: stereographic projection.



Ex: $M = \mathbb{R}P^n$ and $S = \{[x_0, \dots, x_n] \in \mathbb{R}P^n : x_n = 0\} \cong \mathbb{R}P^{n-1}$.

$$U_i = \{x_i \neq 0\} \subset \mathbb{R}P^n, \quad \varphi_i([x_0, \dots, x_n]) = \frac{1}{x_i} (x_1, \dots, \hat{x}_i, \dots, x_n)$$

$$\Rightarrow \varphi(U_i) = \mathbb{R}^n \text{ and } \varphi(U_i \cap S) = \{x \in \mathbb{R}^n : x_n = 0\},$$

Repeat for all $i=0, \dots, n$ and then get adapted charts covering S .

Prop: Let $S^{n-k} \subset M^n$ be an embedded submanifold. The adapted charts (U, φ) induce charts for S given by

$$U \cap S \xrightarrow[\varphi]{\cong} \varphi(U) \cap (\mathbb{R}^{n-k} \times \{0\}) \xrightarrow{\cong} \text{open set in } \mathbb{R}^{n-k}$$
$$(x_1, \dots, x_n) \longmapsto (x_1, \dots, x_{n-k})$$

These give S a manifold structure.

* FIBERS & IMAGES OF MAPS

Prop: If $f: M \rightarrow N$ is a smooth map and $Df(x): T_x M \rightarrow T_{f(x)} N$ has constant rank k on M , then $f^{-1}(q) \subset M$ is an embedded submanifold of codim k ($\forall q \in f(M)$).

Pf: Given $x \in f^{-1}(q)$, by the Constant Rank Thm, there exists charts (U, φ) around x and (V, ψ) around q such that

(i) $f(U) \subset V$ and $\varphi(x) = 0$ and $\psi(q) = 0$

← Can assume they are centered →

(ii) $\psi \circ f \circ \varphi^{-1}: \varphi(U) \rightarrow \psi(V)$ is of the form

$$(x_1, \dots, x_m) \mapsto (x_1, \dots, x_n, 0, \dots, 0)$$

Then $\varphi(U \cap f^{-1}(q)) = \{x \in \varphi(U) : x_1 = \dots = x_n = 0\}$

0 is the image of q under ψ

So, up to permutations of coordinates (which is a diffeo of $\mathbb{R}^m \dots$), (U, φ) is an adapted chart.

Ex: $f: \mathbb{R}^n \rightarrow \mathbb{R}$, $(x_1, \dots, x_n) \mapsto \sum_i x_i^2 = q = r^2$

Then $Df(x) = (2x_1, \dots, 2x_n)$ has rank 1 everywhere except at zero; i.e., $\forall x \in \mathbb{R}^n \setminus \{0\} = \mathbb{R}^n \setminus f^{-1}(0)$.

So, $f|_{\mathbb{R}^n \setminus f^{-1}(0)}$ has constant rank 1

$\Rightarrow f^{-1}(q) \simeq S^{n-1}(\sqrt{q})$ is an embedded submanifold $\forall q > 0$.
radius

Def: Let $f: M \rightarrow N$ be a smooth map. A point $x \in M$ is

- regular point (of f) if $Df(x)$ is surjective (i.e., if $\text{rank } Df(x) = \dim N$)
- critical point (of f) otherwise

If all points in the fiber $f^{-1}(q)$ are regular, then

we say q is a regular value. Otherwise, we say q is a critical value.

FACT: If $f: M \rightarrow N$ is a smooth map and $q \in f(M)$ is a regular value, then $f^{-1}(q) \subset M$ is an embedded submanifold of $\text{codim} = \dim N$.

Pf: B/c of the fact that

$$\text{rank } Df(x) = \kappa \Rightarrow \text{rank } Df(y) \geq \kappa \quad \forall y \text{ in an open neighb. of } x$$

So, $U := \{x \in M : Df(x) \text{ is surjective}\}$ is open in M around $f^{-1}(q)$. So we can apply the prop. from two pages ago. $\square$



Def: A smooth map $f: M \rightarrow N$ with constant rank is called

- a smooth SUBMERSION iff $Df(x)$ is surjective $\forall x \in M$
i.e., iff $\text{rank } Df(x) = \dim N$ at all points $x \in M$.
- a smooth IMMERSION iff $Df(x)$ is injective $\forall x \in M$
i.e., iff $\text{rank } Df(x) = \dim M$ at all points $x \in M$.
- a smooth EMBEDDING iff f is an injective immersion and it is a homeomorphism onto $f(M)$ (w.r.t. to the subspace topology of $f(M) \subset N$).

Prop: If $f: M \rightarrow N$ is a smooth embedding, then $f(M) \subset N$ is an embedded submanifold.

Pf: Let $x \in M$. By the Constant Rank Thm, there exists charts

$$x \in (U, \varphi) \text{ and } (V, \psi) \ni f(x)$$

s.t.

$$(i) f(U) \subset V \text{ and } \psi \circ f \circ \varphi^{-1}(y_1, \dots, y_m) = (y_1, \dots, y_m, 0, \dots, 0)$$

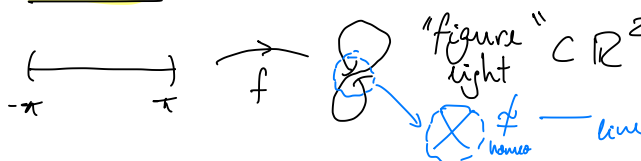
$$(ii) \psi(f(U)) = \{y \in \psi(V) : y_{m+1} = \dots = y_n = 0\}$$

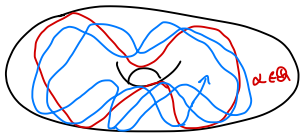
$$\stackrel{''}{=} \psi(f(\varphi^{-1}(\psi(U))))$$

Since $f: M \xrightarrow{\cong} N$ is a homeo., $f(U) = f(M) \cap W$, where $W \subset N$ is open. Set $V' := W \cap V$. Then $(V', \psi|_{V'})$ is a chart around $f(x)$ s.t.

$$\begin{aligned} \psi(V' \cap f(M)) &= \psi(f(U)) \\ &= \{y \in \psi(V') : y_{m+1} = \dots = y_n = 0\} \end{aligned}$$

EXAMPLES: (for what can fail if $f: M \rightarrow f(M)$ is not homeo).

 "figure eight" $\subset \mathbb{R}^2$, $f(t) := (\sin 2t, t)$ is an injective immersion but not a homeo $M \rightarrow f(M)$



$f: \mathbb{R} \rightarrow S^1 \times S^1$, $f(t) = (e^{it}, e^{i\alpha t})$
with $\alpha \in \mathbb{R}$ fixed.

$\alpha \in \mathbb{Q} \Rightarrow f(\mathbb{R})$ is an embedded S^1

$\alpha \notin \mathbb{Q} \Rightarrow f(\mathbb{R})$ is dense and not open in $S^1 \times S^1$, so
it is not an embedded submanifold.

LECTURE 9

COBORDISMS

Oct 4th, 2024

Facts: (1) If $S \subset N$ is an embedded submanifold, then $\exists!$ smooth structure on S making the inclusion map $S \hookrightarrow N$ an emb.

(2) If $f: M \rightarrow N$ is an embedding, then $f(M) =: S \subset N$ is an embedded submanifold and $f: M \rightarrow f(M) \subset N$ is a diffeo. w.r.t. the smooth structure on $f(M)$ as in (1).

————— " —————

* MANIFOLDS w/ BOUNDARY

Def: A manifold w/ boundary is the same as a manifold but that is locally modelled on $\mathbb{H}^m := \{(x_1, \dots, x_m) \in \mathbb{R}^m : x_m \geq 0\}$.

$\Rightarrow$ Can make sense of a smooth atlas here

4/10

Def: Let M be a smooth mfd w/ boundary, then

- $x \in \text{int } M$ if $\varphi(x)_m > 0$ for some (or equiv. any) chart (U, φ) .
 $\leftarrow m\text{-th coordinate}$
- $x \in \partial M$ if $\varphi(x)_m = 0$ for some (or equiv. any) chart (U, φ) .

Prop: Charts for M^m restrict to charts for ∂M making ∂M an $(m-1)$ -dimensional mfd w/out boundary. $\partial^2 = \emptyset$.

Ex: $M = \text{Möbius band}$, $\partial M = S^1$.



$\longrightarrow S^1$ is a nontrivial fiber bundle

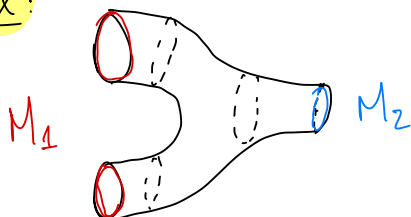
If it were, it would be $S^1 \times [0, 1]$.

But $\partial(S^1 \times [0, 1]) = S^1 \sqcup S^1 \not\hookrightarrow \partial M = S^1$.

* COBORDISMS:

Def: Compact n -mfds (without boundary) M_1 and M_2 are cobordant iff $\exists$ a compact $(n+1)$ -mfd N s.t. $\partial N \cong M_1 \sqcup M_2$
essential

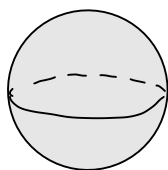
Ex:



$\Rightarrow S^1 \sqcup S^1$ and S^1 are cobordant.

Ex: $M_1 := \partial B$

$M_2 := \emptyset$



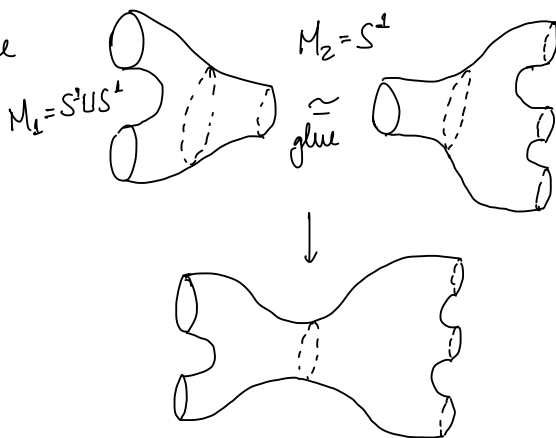
$\Rightarrow S^2$ and $\emptyset$ are cobordant

We say S^2 is NULL-COBORDANT

Prop: Cobordance is an equivalence relation.

Pf: • Reflexive ✓

• Transitive



$M_3 = S^1 \cup S^1 \cup S^1$

NOTATION: $\mathcal{Q}^n :=$ cobordism classes of compact n -manifolds.

GROUP STRUCTURE: $[M_1] + [M_2] := [M_1 \sqcup M_2]$

Well-defined: $\partial N_1 \cong M_1 \sqcup M'_1$ and $\partial N_2 \cong M_2 \sqcup M'_2$, then

$$\begin{aligned} \text{take } \partial(N_1 \sqcup N_2) &= \partial N_1 \sqcup \partial N_2 \cong (M_1 \sqcup M'_1) \sqcup (M_2 \sqcup M'_2) \\ &\cong (M_1 \sqcup M_2) \sqcup (M'_1 \sqcup M'_2) \end{aligned}$$

Prop: $x+x=0 \quad \forall x \in \mathcal{Q}^n$.

Pf: $x = [M] \Rightarrow x+x = \underbrace{[M \sqcup M]}_{\substack{\uparrow 2 \\ \partial(M \times [0,1])}} = [\emptyset] = 0$

NOTE: $\mathcal{Q}^* := \bigoplus_{n \geq 0} \mathcal{Q}^n$ becomes a graded ring with multiplication given by: $\underbrace{[M_1]}_{\substack{\uparrow \\ \mathcal{Q}^{m_1}}} \cdot \underbrace{[M_2]}_{\substack{\uparrow \\ \mathcal{Q}^{m_2}}} = \underbrace{[M_1 \times M_2]}_{\substack{\uparrow \\ \mathcal{Q}^{m_1+m_2}}}$

Well-defined: $\partial N_1 \simeq M_1 \sqcup M'_1$, $\partial N_2 \simeq M_2 \sqcup M'_2$

$[M_1 \times M_2] = [M'_1 \times M_2]$ since $\partial(N_1 \times M_2) = (\partial N_1) \times M_2$

Same for $[M'_1 \times M_2] = [M'_1 \times M_2]$

$$\simeq M_1 \times M_2 \sqcup M'_1 \times M_2$$

Commutative ring: b/c $M_1 \times M_2 \simeq M_2 \times M_1$

Unital: unit = $[*]$ one-point space

Thm: (Poincaré-Thom) The cobordism ring is a countably generated polynomial ring over $\mathbb{F}_2$ with generators in every degree $n \neq 2^k - 1, k \in \mathbb{N}$.

$$\hookrightarrow \mathcal{Q}^* = \mathbb{F}_2 [x_2, x_4, x_5, x_6, x_8, \dots]$$

$\uparrow \quad \uparrow$
deg of generator $\leftrightarrow$ dimension

NOTE: (1) $\Omega^0 = \mathbb{Z}/2\mathbb{Z}$ consisting of $0 = [\emptyset]$ and $1 = [*]$.

(2) $\Omega^1 = 0$ ← Classification of 1-dim compact manifolds w/out bdy $\Rightarrow$ only have S^1 which is the bdy of the disk $\Rightarrow$ null-cobordant.

(3) $\Omega^2 = \mathbb{Z}/2\mathbb{Z} = \langle x_2 \rangle$, $x_2 = [\mathbb{R}P^2]$.

RMK: $[\Sigma] = 0 \quad \forall \Sigma$ oriented surface.

Classification:



NOTE: $\Omega^4 = \{x_2^2, x_4, x_2^2 + x_4, 0\}$.

$$x_2^2 + x_4 = [\mathbb{R}P^2 \times \mathbb{R}P^2 \sqcup \mathbb{R}P^4] = [\mathbb{R}P^2 \times \mathbb{R}P^2 \# \mathbb{R}P^4].$$

* MAPS BETWEEN MANIFOLDS w/ BOUNDARY:

Prop: Let M be a manifold ($\partial M = \emptyset$) and $f: M \rightarrow \mathbb{R}$ smooth and $a \leq b$ both regular values of f . Then $f^{-1}([a, b])$ is a smooth n -manifold embedded in M and with boundary $= f^{-1}(a) \cup f^{-1}(b)$.

Ex: $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, $(x, y, z) \mapsto x^2 + y^2 - z^2$. Apply proposition to find that $f^{-1}([-1, 1])$ is a manifold with boundary given by $\underline{f^{-1}(-1)} \cup \underline{f^{-1}(1)} = \underline{\{x^2 + y^2 = z^2 - 1\}} \cup \underline{\{x^2 + y^2 = z^2 + 1\}}$.



Note $f^{-1}(0) = \text{singularity}$.

Q: $[M_1 \cup M_2] = [M_1 \# M_2]$.

P: $M_1 \cup M_2 = \text{prop.} =$

LECTURE 10

Oct 10th, 2024

Smooth maps $f: M^m \rightarrow N^n$ are modeled on $\mathbb{R}^m \xrightarrow{\text{linear}} \mathbb{R}^n$ if the rank Df is constant.

← If it's not constant near $p \in M$,
then we cannot classify the form of
the maps $\Rightarrow$ classification problem

Ex: (MORSE LEMMA) Let $f: M \rightarrow \mathbb{R}$ be C^∞ st. $\left\{ \begin{array}{l} \text{(i)} Df(x) = 0 \\ \text{(ii)} \left[\frac{\partial^2 f}{\partial x_i \partial x_j} \right] \text{ is} \end{array} \right.$
nondegenerate at p
of signature $(k, n-k)$
of + $\uparrow$ $\leftarrow$ # of - in the Hessian

Then $\exists$ coords $(x^1, \dots, x^n)$ about p st.

$$f(x^1, \dots, x^n) = f(p) + \sum_{i=1}^k (x^i)^2 - \sum_{j=k+1}^n (x^j)^2.$$

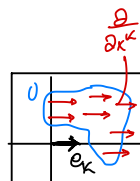
→ Allows us to infer the behavior of a fct.
at the nbhd of a point p .

* VECTOR FIELDS: A vec. field on some $U \subseteq_{\text{open}} V$ (V is a $\mathbb{R}$ -vec. space) is just $X: U \rightarrow V$ vector valued fct.

• If we choose a basis $(e_1, \dots, e_n)$ for V , it induces a dual basis $(x^1, \dots, x^n)$.
coord. syst. on U

• Then we have constant vec. fields $U \longrightarrow V$
 $p \longmapsto e_k$

These constant vec. fields are denoted $\frac{\partial}{\partial x^k}$



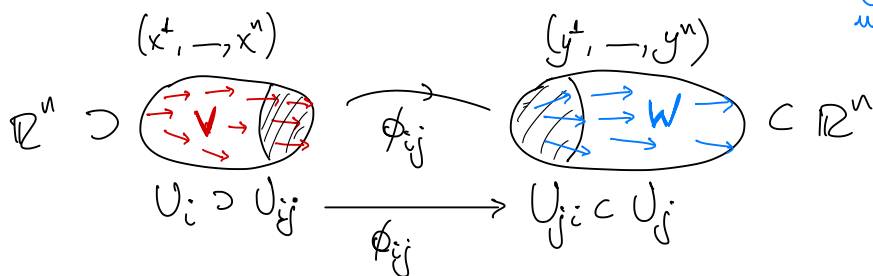
• Reason for notation: can identify $\frac{\partial}{\partial x^k}$ with the directional derivative of functions.

$$\left\{ \begin{array}{c} \text{vector fields} \\ \text{on } U \end{array} \right\} \xleftrightarrow{1-1} \left\{ \begin{array}{c} \text{Derivations} \\ \text{of } C^\infty(U, \mathbb{R}) \end{array} \right\}$$

Def: A derivation of an algebra A is a linear map $D: A \rightarrow A$ s.t. $D(ab) = (Da)b + aDb$ (Leibniz Rule)

• GLuing: Under what conditions does

$$V = \sum_{i=1}^n v^i(x^1, \dots, x^n) \frac{\partial}{\partial x^i} \text{ glue to } W = \sum_{i=1}^n w^i(y^1, \dots, y^n) \frac{\partial}{\partial y^i}$$



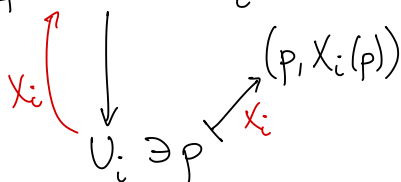
using ϕ_{ij}^* $\frac{\partial}{\partial y^i} = \sum_j \frac{\partial x^j}{\partial y^i} \frac{\partial}{\partial x^j}$

change bases: $\frac{\partial}{\partial y^i} = \sum_j \frac{\partial x^j}{\partial y^i} \frac{\partial}{\partial x^j}$

$\Rightarrow$ Condition is that we can write:

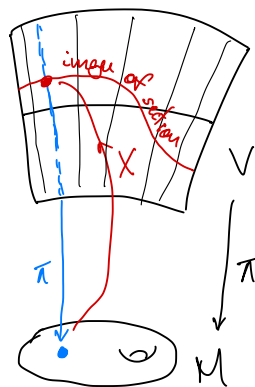
$$V^i(x^1, \dots, x^n) = \sum_{k=1}^n W^k(y^1(x^1, \dots, x^n), \dots, y^n(x^1, \dots, x^n)) \frac{\partial x^i}{\partial y^k}(x^1, \dots, x^n)$$

Upshot: The vector field $X_i: U_i \subset \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a "section" of $TU_i = U_i \times \mathbb{R}^n$



Def: A section of a tangent bundle $\pi: V \rightarrow M$ is a C^∞ map $X: M \rightarrow V$ s.t. $\pi \circ X = \text{Id}_M$.

Section hits each fiber $\rightarrow$ precisely at 1 point



Thus: given vector fields X_i, X_j on U_i, U_j , these glue to a global section iff $D(\phi_{ij})_{p \in U_{ij}}(X_i(p)) = X_j(\phi_{ij}(p))$

$$\begin{array}{ccccc} TU_i \supset TU_{ij} & \xrightarrow[\phi_{ij}, D\phi_{ij}]{\cong} & TU_{ji} \subset TU_j & & \\ \downarrow \pi_i & & \downarrow & & \downarrow \pi_j \\ U_i \supset U_{ij} & \xrightarrow[\phi_{ij}]{\cong} & U_{ji} \subset U_j & & \end{array}$$

Red arrows labeled X_i and X_j point from U_i and U_j respectively to TU_i and TU_j .

Def: A vector field on a C^∞ mfd M is a C^∞ section of TM .

The space of all vec. fields on M is denoted $\Gamma(M, TM) = \mathcal{X}(M)$.

$$\begin{array}{c} TM \\ \pi \downarrow \\ M \end{array} \quad \begin{array}{c} \text{red arrow } X \\ \pi \circ X = Id_M \end{array}$$

Annoying Bmn: Vector fields may not be pushed or pulled along C^∞ maps (unless f is invertible)

$$\begin{array}{ccc} TM & \xrightarrow{Df} & TN \\ \downarrow \text{blue } X & & \downarrow \text{red } Y \\ M & \xrightarrow{f} & N \end{array}$$

$$f: M \xrightarrow{C^\infty} N$$

Def: $X \in \mathcal{X}(M)$ is " f -related" to $Y \in \mathcal{X}(N)$ when

$$Df \circ X = Y \circ f.$$

In the special case of f being a diffeomorphism, we can push and pull via

$$f_* X := Df \circ X \circ f^{-1}, \quad f^* Y := (Df)^{-1} \circ Y \circ f$$

Ex: (Vector field on S^1) Take $X_0 = \frac{\partial}{\partial x}$ const. vec field on U_0
 $S^1 = U_0 \cup U_1$

$$\begin{array}{c} \text{red arrows} \\ X_0 = \frac{\partial}{\partial x} \text{ const. vec. field} \\ \rightarrow U_0 = \mathbb{R}_x \supset \mathbb{R}_{\neq 0} \end{array}$$

$$\begin{array}{c} \text{blue arrows} \\ U_1 = \mathbb{R}_y \supset \mathbb{R}_{\neq 0} \\ X_1 = -y^2 \frac{\partial}{\partial y} \end{array}$$

$$\phi: x \mapsto x^{-1}$$

$$\begin{aligned} \phi: x &\mapsto x^{-1} \\ D\phi: v &\mapsto \left[\frac{\partial \phi}{\partial x} \right] v \\ &= [-x^{-2}] v \end{aligned}$$

Gluing: $x \neq 0 \sim y \neq 0$
 $\text{iff } y = x^{-1}$

By the gluing construction for vec fields above,

$$(\mathcal{D}\phi_{ij})_{p \in U_j}(X_i(p)) = X_j(\phi_{ij}(p)) \rightsquigarrow [-x^{-2}]_1 = X_1$$

$$X_0 = 1 \cdot \frac{\partial}{\partial x}$$

$$\Rightarrow X_1 = -x^{-2} \frac{\partial}{\partial y} = -y^2 \frac{\partial}{\partial y}$$

Since smooth, we can extend it
to all of U_L (could be non-smooth
and then we only have it on the
gluing region and not on all of S^1)

LECTURE 11

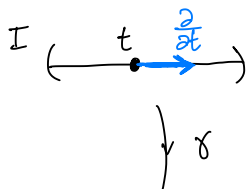
Oct 11, 2024

* FLOW OF A VECTOR FIELD

$I = (a, b)$ including (a, ∞)
 $(-\infty, b)$
 $(-\infty, \infty)$
...

Def: A path or curve in M is a map $\gamma: I \subset \mathbb{R} \rightarrow M$.
The velocity of this path at time $t \in I$ is

$$(\mathcal{D}\gamma)_t: T_t I \rightarrow T_{\gamma(t)} M$$

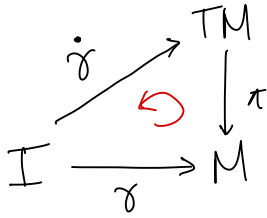


"
 $\mathbb{R}$

$$1 =: \frac{\partial}{\partial t} \longmapsto \mathcal{D}\gamma_t \left(\frac{\partial}{\partial t} \right) = \dot{\gamma}(t)$$



NOTE: The velocity defines a lift of γ to a path in TM



i.e., the diagram commutes

Def. Let $X \in \mathcal{X}(M)$. The path γ is called an INTEGRAL CURVE of X if its velocity coincides with X ; i.e.,

$$\dot{\gamma}(t) = X(\gamma(t)) \quad (*)$$

In coordinates: $(U, \varphi) \quad (x^1, \dots, x^n)$,

$$X = X^1 \frac{\partial}{\partial x^1} + \dots + X^n \frac{\partial}{\partial x^n} \quad , \quad X^i = X^i(x^1, \dots, x^n) \text{ smooth}$$

$$\varphi \circ \gamma = (\gamma^1(t), \dots, \gamma^n(t))$$

So, we can write $(*)$ as:

$$(*) \quad \begin{aligned} \frac{d}{dt} \gamma^1(t) &= X^1(\gamma^1(t), \dots, \gamma^n(t)) \\ &\vdots \\ \frac{d}{dt} \gamma^n(t) &= X^n(\gamma^1(t), \dots, \gamma^n(t)) \end{aligned}$$

system of n
coupled 1st
order nonlinear
ODEs

Thm: (Existence and uniqueness of solutions to ODEs)

Let $X \in \mathcal{X}(V)$, $V \subset_{\text{open}} \mathbb{R}^n$. For each $x_0 \in V$, $\exists$ a nbhd U , $x_0 \in U \subset V$, and $\varepsilon > 0$ and a smooth map

$$\Phi : (-\varepsilon, \varepsilon) \times U \longrightarrow V$$

← implies solution depends smoothly on initial conditions

$$(t, x) \longmapsto \varphi_t(x)$$

such that $\forall x \in U$, the curve $t \mapsto \varphi_t(x)$ is an integral curve of X with initial condition x ; i.e., $\varphi_0(x) = x$.

Uniqueness: if $(U', \varepsilon', \Phi')$ is another tuple satisfying the above, then $\Phi = \Phi'$ on a common domain.

Corollary: Let $X \in \mathcal{X}(M)$. Then, there exists a nbhd U , $\{0\} \times M \subset U \subset \mathbb{R} \times M$, and a C^∞ map

$$\Phi : U \longrightarrow M$$

such that

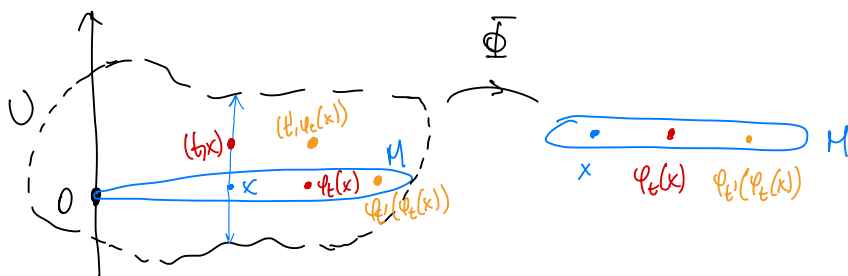
(i) $(\mathbb{R} \times \{x\}) \cap U$ is an interval about 0 in $\mathbb{R}$. (ensures U is "connected")

(ii) $t \mapsto \varphi_t(y) = \Phi(t, y)$ is an integral curve of X

(iii) $\varphi_0(y) = y$ starting at y

(iv) if (t, x) and $(t', \varphi_t(x))$ and $(t+t', x)$ are in U , then $\varphi_{t+t'}(x) = \varphi_{t'}(\varphi_t(x))$.

Uniqueness: if (U, Φ) satisfies the above and satisfies (i), (ii), (iii), then it must satisfy (iv) and $\Phi = \Phi'$ on a common domain.



Pf: Using Exist. & Uniq. of ODEs, find an open cover $(U_i)_{i \in I}$ of M , $\varepsilon_i > 0$ $i \in I$, and maps $\Phi_i : (-\varepsilon_i, \varepsilon_i) \rightarrow M$ as in thm.

By uniqueness Φ_i must agree with Φ_j on

$$((- \varepsilon_i, \varepsilon_i) \times U_i) \cap ((- \varepsilon_j, \varepsilon_j) \times U_j).$$

Then, we get a well-def. map on the union:

$$\Phi : \underbrace{\bigcup_{i \in I} (-\varepsilon_i, \varepsilon_i) \times U_i}_{=: U} \longrightarrow M.$$

By construction, Φ satisfies (i), (ii), (iii).

Verify (iv), note that we can compare

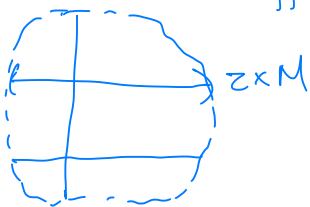
$$\begin{aligned} \tau &\mapsto \varphi_\tau(\varphi_t(x)) && \leftarrow \text{Both are integral curves w/} \\ & && \text{initial condition } \varphi_t(x). \text{ Thus,} \\ \tau &\mapsto \varphi_{\tau+t}(x) && \leftarrow \text{by uniqueness, they must coincide.} \end{aligned}$$

Similar analysis gives uniqueness of flows.

□

Proposition: There exists a maximal flow (constructed by taking the union of all possible flows). This flow is called: maximal local 1-parameter group of diffeomorphisms (bad terminology...)

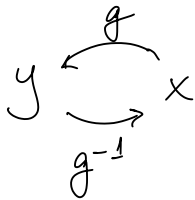
Note: if $t \pm z \in U$ then $\varphi_z: M \rightarrow M$ is defined and is a diffeomorphism (smooth inverse is $\varphi_{-z}: M \rightarrow M$).



$$\mathcal{X}(M) \leftrightarrow \text{Diff}(M)$$

Infinitesimal symmetries Global symmetries

Def: A groupoid is a category in which every arrow has an inverse g^{-1}



For maximal flow: view elements of U as arrows, where

$$U \ni (t, x) \quad \begin{array}{l} \text{source}(t, x) = x \\ \text{target}(t, x) = \varphi_t(x) \\ \text{Id}_x = (0, x) \end{array} \quad \begin{array}{l} \text{inverse}(t, x) = (-t, \varphi_t(x)) \\ \text{Composition:} \\ (t', \varphi_t(x))(t, x) = (t' + t, x) \end{array}$$

$$U \times \begin{array}{c} \xrightarrow{\text{target}} \\ \xleftarrow{\text{source}} \end{array} M \quad \text{Unique flow groupoid of } x$$

SPECIAL CASE:

Def: If $U^X = \mathbb{R} \times M$ then X is called a COMPLETE vector fields and we obtain a 1-parameter ^(sub)group of diffeos.

$$\mathbb{R} \ni t \longmapsto \varphi_t^X \in \text{Diff}(M)$$

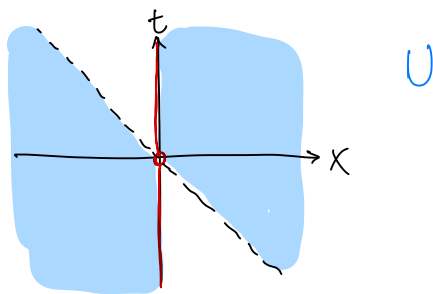
$$t+t' \longmapsto \varphi_{t+t'}^X = \varphi_t^X \circ \varphi_{t'}^X = \varphi_{t'}^X \circ \varphi_t^X$$

Sometimes written $\varphi_t^X = e^{tX}$ $\leftarrow$ 1-param. group of diffeos. of complete vector fields

Ex: Constant vector field $X = \frac{\partial}{\partial x}$ is complete in $\mathbb{R}$

with flow $\varphi_t^X(y) = t + y$.

BUT $X = \frac{\partial}{\partial x}$ is incomplete in $\mathbb{R} \setminus \{0\}$



Thm: If M is compact (w/out bdy), then all $X \in \mathcal{X}(M)$ are complete.

LECTURE 12

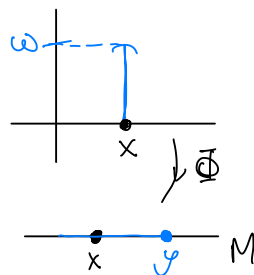
Oct 17th, 2024

Thm: On a compact manifold, any $X \in \mathcal{X}(M)$ is complete.

PF: By contradiction, assume Φ is the maximal flow of X . If X is not complete, then

$\exists x \in M$ and WLOG $w > 0$ s.t.
 $U \cap (\mathbb{R} \times \{x\}) = \text{open interval w/ upper boundary } w$

WIS: this contradicts maximality.



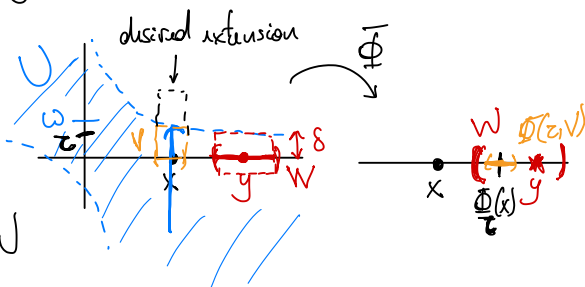
1. By compactness, as $t \rightarrow w$, $\Phi(t, x) - y$ is an accumulation point.

(Idea: flow is defined at y ! Extend flow at x by flowing almost to w , continue using flow near y .)

2. $\exists \delta > 0$ and a nbhd W of y s.t. $(-\delta, \delta) \times W \subset U$.

Since W is open, $\exists z \in (w - \delta, w)$ s.t. $\Phi(z, x) \in W$. Moreover, $\exists$ nbhd V of x s.t.

$\{z\} \times V \subset U$ and $\Phi(z, V) \subset W$



3. Given these choices, enlarge U by doing:

$$\tilde{U} = U \cup ((z-\delta, z+\delta) \times V)$$

$$\tilde{\Phi}(t, z) = \begin{cases} \Phi(t, z), & \text{if } (t, z) \in U \\ \Phi(t-z, \Phi(z, z)) & \text{if } (t, z) \in \underbrace{(z-\delta, z+\delta) \times V} \end{cases}$$

Extension of U since $z+\delta > \omega$

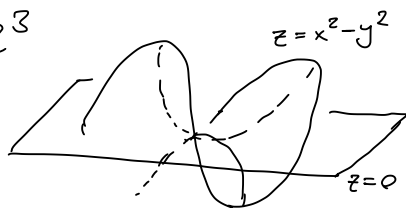
* **TRANSVERSALITY**: Unlike in the linear category, where $U_1, U_2 \subset V$ intersect in a linear subspace $U_1 \cap U_2$, for manifolds, this fails! ← Unless we require a special relationship between submanifolds

↳ Manifolds are not "closed under intersection".

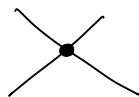
Ex: $\{z = x^2 - y^2\} \cap \{z = 0\}$ in $\mathbb{R}^3$

surface
codim 1

surface
codim 1



Intersection:



← Not a mfd

Note: $\{z^2 = x^2 - y^2\} \cap \{z = t\}$

$t = 0$: singular

$t = 1$: Hyperbola

$t = -1$: Hyperbola

} smooth 1-d
submanifolds
(codim 2)

(Transverse intersections)

Thm: If K, L are smooth submanifolds of M^n of codim $k+l$ are TRANSVERSE, then $K \cap L$ is either empty or a submanifold of codim $k+l$.

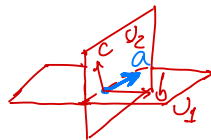
Idea: submfd of codim $k = k$ indep constraints in M
 " " " $l = l$ " " "
 If k -constraints and l -constraints are independent (transversality), then $K \cap L$ imposes all $k+l$ constraints gives a submfd of codim $k+l$.

Def: K, L submfds of M are transverse if $\forall p \in K \cap L$, $T_p K$ and $T_p L$ are transverse in $T_p M$.

From linear algebra: two linear subspaces $U_1, U_2 \subset V$ are transverse if $U_1 + U_2 = V$.

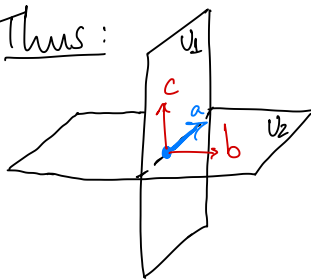
e.g.: $V + V = V$
 ↗ transverse

↖ not direct sum
 (intersection need
 not be zero)



$$\dim U_1 \cap U_2 = a = (a+b) + (a+c) - (a+b+c) \\ = \dim U_1 + \dim U_2 - \dim V$$

Thus:



$$\dim U_1 \cap U_2 = \dim U_1 + \dim U_2 - \dim V$$

$$\text{codim } U_1 \cap U_2 = b + c = \text{codim } U_1 + \text{codim } U_2$$

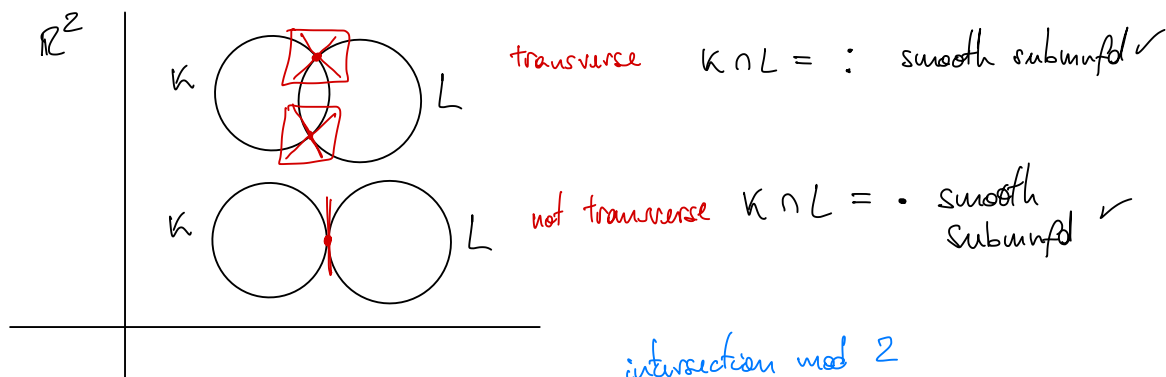
constraints
 def. $U_1 \cap U_2$

constraints
 def. U_1

constraints
 def. U_2

$\Rightarrow$ "dimension of transverse intersection is the expected dim."

! WARNING: $K \cap L$ may be a smooth submanifold even if intersection is not transverse.



$\Rightarrow$ "Transversality gives control over intersection # " in the case $\dim K \cap L = 0$.

Note: in order for two closed loops in the plane to be transverse they must intersect in an even # of pts.

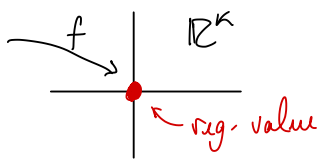
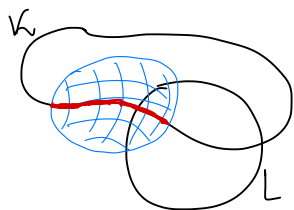
Pf: (of thm) K, L are submanifolds of codim k, l . So, $\exists$ submanifold charts $(U(x^1, \dots, x^n))$ and $(V(y^1, \dots, y^n))$ in M s.t.
 $K = \{x^1 = \dots = x^k = 0\}$, $L = \{y^1 = \dots = y^l = 0\}$.

In other words, $\exists f: U \rightarrow \mathbb{R}^k$ s.t. 0 is a regular value

$$g: V \rightarrow \mathbb{R}^l$$

$$K \cap U = f^{-1}(0)$$

$$L \cap V = g^{-1}(0)$$



NB: on $U \cap V$, combine the constraint functions

$$(f, g): U \cap V \rightarrow \mathbb{R}^k \times \mathbb{R}^l.$$

$\alpha: (K \cap L) \cap (U \cap V) = (f, g)^{-1}(0, 0)$ and (f, g) is a submersion, so $K \cap L$ is a submfd.

Only remains to show that $(0, 0) \in \mathbb{R}^{k+l}$ is a reg. value of (f, g)

WTS: $D_x(f, g)$ is onto for all $x \in U \cap V \cap K \cap L$

$$D_x(f, g): T_x M \stackrel{\cong}{\rightarrow} \mathbb{R}^{k+l}$$

$$\ker D_x(f, g) = \underbrace{(\ker D_x f)}_{T_x K} \cap \underbrace{(\ker D_x g)}_{T_x L}$$

$$\begin{aligned} \text{Transversality} \Rightarrow \dim \ker(D_x(f, g)) &= \text{codim} \ker(D_x(f, g)) \\ &\stackrel{\text{transversality}}{=} \text{codim}(\ker D_x f) \\ &\quad + \text{codim}(\ker D_x g) \\ &= k + l \end{aligned}$$

LECTURE 13

Oct 18, 2024

Thm: $K, L \subset M$ are transverse, then either $K \cap L$ is empty or a submfd of $\text{codim}(K \cap L) = \text{codim } K + \text{codim } L$.

Ex: In $\mathbb{R}^6$

K	L
0	0
1	1
2	2
3	3
4	4
5	5
6	6

* nonempty $\cap$

Ex: $\mathbb{R}^{10} \setminus \{0\} = \mathbb{C}^5 \setminus \{0\} =: M$

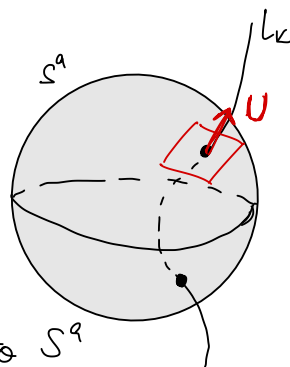
$K := S^9 = \left\{ (z_1, \dots, z_5) : \sum_{i=1}^5 |z_i|^2 = 1 \right\}$ hypersurface (codim 1)

$L_k := \left\{ (z_1, \dots, z_5) : \underbrace{z_1^2 + z_2^2 + z_3^2 + z_4^2 + z_5^{6k-1}} = 0 \right\}, k \in \mathbb{N}$

(think of $f: \mathbb{R}^{10} \rightarrow \mathbb{R}^2, f^{-1}(0)$ is a reg. value)

Q: $K \cap L$ (transverse intersection)

$$U = \frac{1}{2} z_1 \partial_{z_1} + \frac{1}{2} z_2 \partial_{z_2} + \frac{1}{2} z_3 \partial_{z_3} + \frac{1}{3} z_4 \partial_{z_4} + \frac{1}{6k-1} z_5 \partial_{z_5}$$



Now, $\text{Re}(U)$ is tangent to L_k but not to S^9

Apply it to the fets that define L_k and S^9

Not: $z = x + iy \rightarrow dz = dx + i dy \rightarrow \frac{\partial}{\partial z} = \frac{1}{2} \left(\frac{\partial}{\partial x} - i \frac{\partial}{\partial y} \right)$

Brieskorn (60s): $K \cap L_\kappa$ for $\kappa = 1, \dots, 28$ are homeomorphic to S^7 .

Kervaire - Milnor: these are all the different smooth structures on S^7 . The smooth structures on S^7 form a group by connected sums

$$S_{\text{top}}^7 \# S_{\text{top}}^7 = S_{\text{top}}^7.$$

In this case $C^\infty\text{-str}(S^7) = \mathbb{Z}/28\mathbb{Z}$

$$(K \cap L_1) \# (K \cap L_1) \equiv_{C^\infty} K \cap L_2$$

We can rephrase transversality of $K, L \subset M$ in terms of the embeddings

$$\underbrace{\iota_K: K \hookrightarrow M}_{\substack{\text{embedding} \\ \text{injective} \\ \text{immersion} \\ \text{homeo. onto image}}} \longleftrightarrow L: \iota_L$$

Need to map the tangent spaces to K and L to M .

$\forall (k, l) \in K \times L$ s.t. $\iota_K(k) = \iota_L(l) =: p \in M$

((k, l) is an "intersection point")

$$\begin{array}{ccc} T_k K & & T_l L \\ & \searrow D_k \iota_K & \swarrow D_l \iota_L \\ & T_p M & \end{array}$$

are transverse; i.e.,

$$\text{im } D_k \iota_K + \text{im } D_l \iota_L = T_p M$$

Transversality in terms of maps now (instead of submanifolds)

Def: Two maps $f: K \rightarrow M$ and $g: L \rightarrow M$ of manifolds are TRANSVERSE if $\forall$ intersection pts.

i.e., $(a, b) \in K \times L$ st. $f(a) = g(b) =: p$

we have $D_a f, D_b g$ are transverse

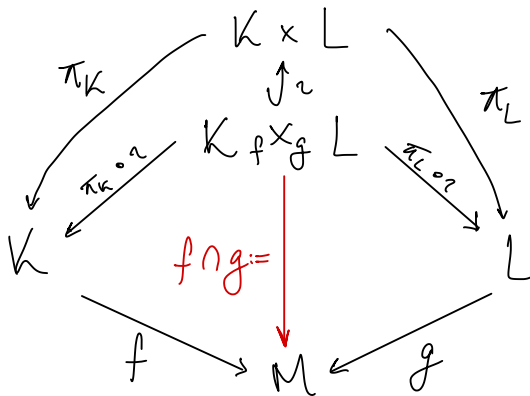
i.e., $\text{im } D_a f + \text{im } D_b g = T_p M$.

↓ slightly improved then

Thm: If $f \in C^\infty(K, M)$ and $g \in C^\infty(L, M)$ are transverse, then their intersection, called the fiber product,

$$K \times_f L = \{ (k, l) \in K \times L : f(k) = g(l) \}$$

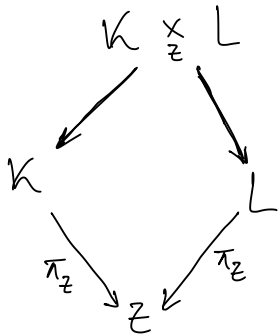
is a smooth submanifold of $K \times L$ equipped with commuting maps



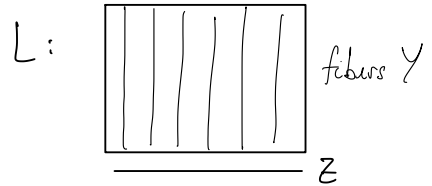
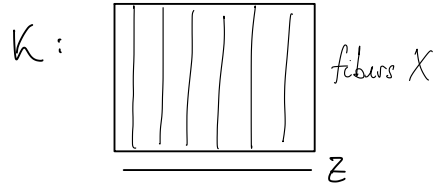
(When maps g, f are understood, we write $K \times_f L = K \times_M L$)

Ex: $K = Z \times X$
 $L = Z \times Y$

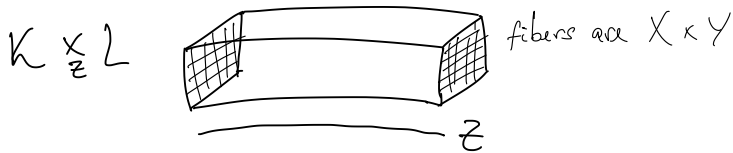
$X, Y, Z \in C^\infty\text{-manifold}$



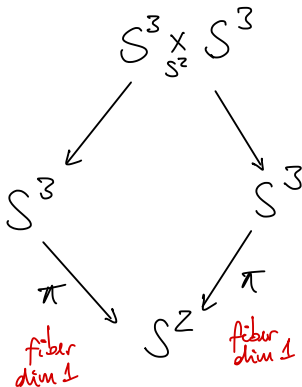
π_Z is a submersion
 (i.e., $D\pi_Z$ is onto) so
 it is transverse to
any map to Z



$K \times_Z L = \{(z, x), (\tilde{z}, y) : z = \tilde{z}\} = Z \times X \times Y.$



Ex: $\pi: S^3 \rightarrow S^2$ Hopf fibration (S^1 fiber bundle)



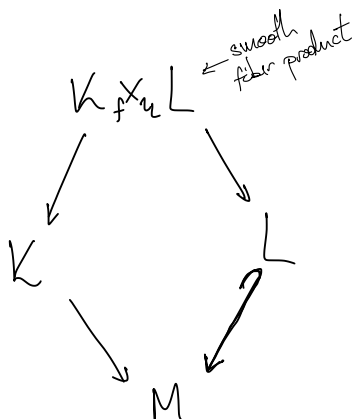
Since π is continuous,
 we have that $\pi \circ \pi$.

This gives a fiber
 $S^3 \times_{S^2} S^3$ bundle with
 fiber $T^2 = S^1 \times S^1$
 $\swarrow \pi \circ \pi$
 fiber dim 1+1 = 2
 S^2
 4d manifold.

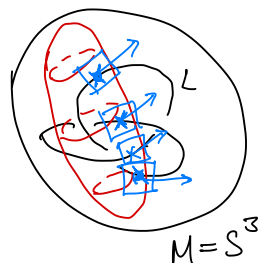
Ex: $L \xrightarrow{z_L} M$ submfd

$K \xrightarrow{f} M$ smooth map transverse to L

e.g., if f is a submersion but this is not always the case



In order for f to be transverse, it needs to provide the tangent directions that are missing from L to complete into $T_p M$.



$$K \times_{f, z_L} L = \{(k, l) : K \times L \text{ s.t. } f(k) = z_L(l)\}^{\rightarrow}$$

$$= f^{-1}(L)$$

Generalizes the regular value theorem.

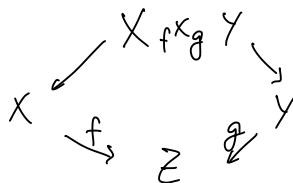
LECTURE 14

Oct 24th, 2024

Transversality

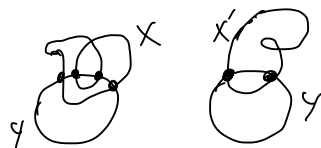
- of manifolds:
- of C^∞ maps:

$$X, Y \subset Z \quad X \cap Y$$



INTERSECTION NUMBER (mod 2): the intersection # of two submanifolds X, Y in Z should be " $= \#$ of intersec. pts."

1. Want X, Y to have $\cap$ intersec. in 0-dim submanifds
i.e., want X, Y to have complimentary dim: $\dim X + \dim Y = \dim Z$
2. Want X, Y compact so the # is finite.



PROBLEM: # not well-def. but it is mod 2.

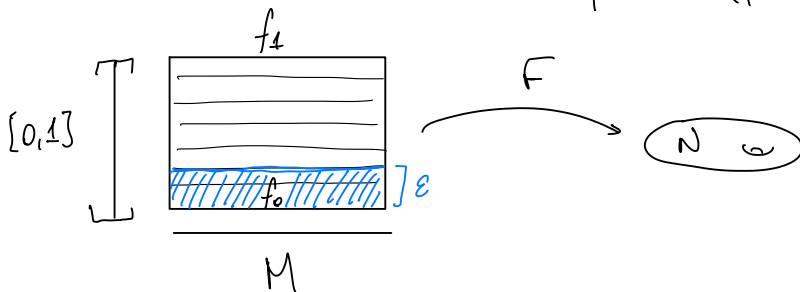
"Q: # mod 2 is independent of perturbations of X, Y ." (i.e., it's stable)

Def: (1) A smooth map $F: M \times [0, 1] \rightarrow N$ is a smooth homotopy from f_0 to f_1 , where

$$f_t = F \circ j_t$$

$$j_t: M \longrightarrow M \times [0, 1]$$

$$p \longmapsto (p, t)$$



(2) A property of smooth maps $f \in C^\infty(M, N)$ is STABLE under perturbations if $\forall$ smooth homotopies f_t , $t \in [0, 1]$, we have

property holds for $f_0 \Rightarrow$ property holds for f_t for some $\varepsilon > 0$, $0 \leq t < \varepsilon$.

Def: (INTERSECTION #) Actual definition of $I_2(X, Y)$ removes the requirement of X, Y being transverse.

Strategy: 1. If X, Y compact are given and are s.t. $\dim X + \dim Y = \dim Z$, deform X via a smooth homotopy until it becomes transverse to Y .

non-transverse maps are measure zero $\rightarrow$ This depends on the fact that $\cap$ is generic in the space of maps [SARD'S THM]

Given any map i_X we can find transverse maps in a nbhd of it

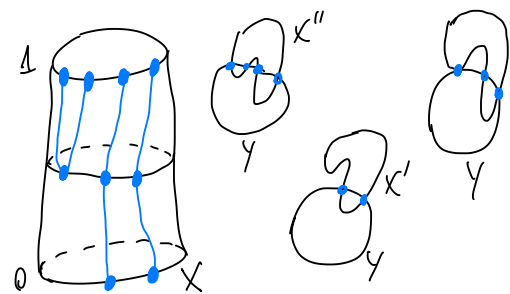
$C^\infty(X, Z)$

maps that fail to be $\cap Y$ are measure zero

Emm: the set of maps $\cap Y$ are dense and have full measure.

After deformation from X to X' , $\# X' \cap Y \in \mathbb{Z}$ is well-defined. But this depends on the deformation.

2. Given two deformations X', X'' of X , each $\cap Y$, what is the relation between $X' \cap Y$ and $X'' \cap Y$?



A: THEY ARE COBORDANT
0-DIM COMPACT MNFDS

cobordism of 0-dim mfds

$C = \text{compact 1-mfld w/ boundary}$

$$0 \cup 0 \cup \dots \cup 0$$

$$[0,1] \sqcup [0,1] \sqcup \dots \sqcup [0,1]$$

$\Rightarrow \# \text{ bdy pts. of } C \Rightarrow \# X' = \# X'' \pmod 2$
must be even

X'

$$\partial C = X' \sqcup X''$$

How to produce such cobordism? We need a C^∞ homotopy

$$J: X \times [0,1] \longrightarrow Z$$

$$J_0 = \iota_{X'} \text{ and } J_1 = \iota_{X''}$$

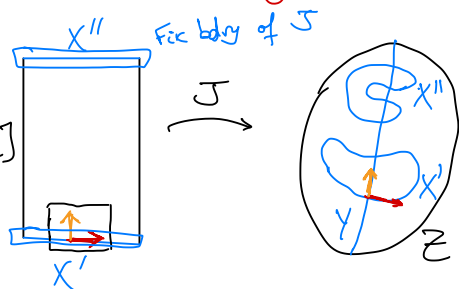
$$(X \times [0,1])_{J \times \iota_Y} Y \longrightarrow Y$$

$$\begin{array}{ccc} \downarrow & & \downarrow \iota_Y \\ X \times [0,1] & \xrightarrow{J} & Z \end{array}$$

Hope: $(X \times [0,1])_{J \times \iota_Y} Y$ is a cobordism.

Problem: We don't know that $(X \times [0,1])_{J \times \iota_Y} Y$ is smooth (e.g., it would be if $J \pitchfork Y$ but we have no guarantee of that). BUT: J_0, J_1 are $\pitchfork Y$.

$J \pitchfork Y$ along the boundary $\{0,1\}$ of the cylinder



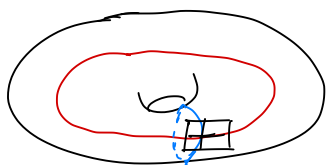
Solution: Same strategy using genericity of $\cap$.

Modify J : find a homotopy from J to J' s.t.
 $J' \nparallel \gamma$.

But: domain of J is a manifold w/ ∂ and so we want to fix $J|_{\partial(M \times [0,1])}$ (version of genericity) (allows us to do that)

[SARD II] Thm: Existence of $\cap$ perturbation w/ bdry condition

Ex: T^2



$$X := S^1 \times \{1\} \subset S^1 \times S^1$$

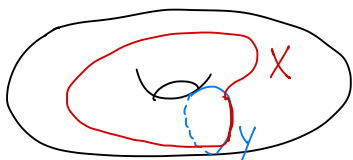
$$Y := S^1 \times \{1\} \subset S^1 \times S^1$$

$$X \cap Y = \{(1,1)\}$$

But $X \nparallel Y$ since $T_{(1,1)} X + T_{(1,1)} Y = T_{(1,1)}(T^2)$

$$\Rightarrow I_2(X, Y) = 1 \pmod{2}$$

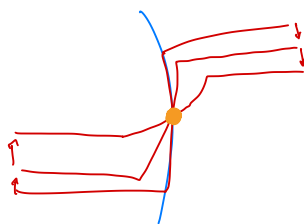
T^2



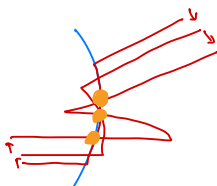
$X \cap Y$ not transverse, ∞ -many intersection pts.

} Apply construction above

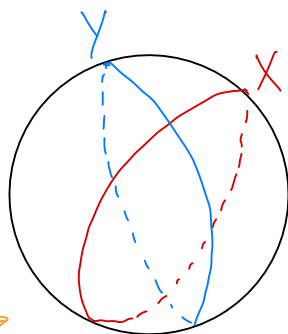
deform X



or...



Ex: S^2



X, Y great circles

$$I_2(X, Y) = 2 = 0 \pmod{2}$$

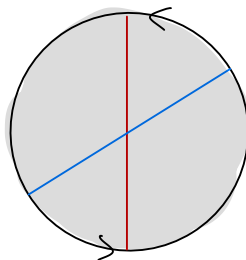
or deform X to a point by smooth homotopy until

$$X' \cap Y = \emptyset.$$

same works for any embedded circles



Ex: $\mathbb{R}P^2$ image of distinct great circles give paths
 $\# X \cap Y = 1 \pmod{2}$



LECTURE 15

Oct 25th, 2024

Def: (INTERSECTION $\#$) X, Y compact f, g smooth s.t. $\dim X + \dim Y = \dim Z$. Then

not necessarily transverse

$$\begin{array}{ccc} X & & Y \\ f \downarrow & & \downarrow g \\ & Z & \end{array}$$

$$I_2(f, g) := \#(X_{f \cdot g} Y) \pmod{2}, \text{ where}$$

f' is any map smoothly homotopic to f and transverse to g .

$$\begin{array}{ccc} X \times Y \supset X \xrightarrow{f' \times g} Y & \longrightarrow & Y \\ \downarrow & & \downarrow g \\ X & \xrightarrow{f'} & Z \end{array}$$

smooth submanifold

Dim: $\dim X + \dim Y = \dim Z$

$\Downarrow$
 $\dim(X_{f' \times g} Y) = 0$

Need to prove:

Claim 1: It is always possible to find $f' \sim f$ (C^∞ homotopy)

Claim 2: For $f' \sim f$ and $f'' \sim f$, $X_{f' \times g} Y$ is cobordant to $X_{f'' \times g} Y$

so that the definition is valid.

Obs: Both claims follow from Sard's theorem.

Ex: A pt $p \in S^1$ can be seen as a map

$$\begin{array}{ccc} \{*\} & \xleftarrow{\quad} & \{p\} \\ & \searrow P & \nearrow \text{Id} \\ & S^1 & \end{array}$$

Note: Id is a submersion, hence $\text{Id} \in \left(\text{any map} \right)_{X \rightarrow S^1}$.

So, we have a single point of intersection.

$\Rightarrow \text{Id}$ is not smoothly homotopic to any constant map.

If $\text{Id} \sim \text{const. map } g: x \mapsto q \in S^1, q \neq p.$

$\Rightarrow *_{\text{p}} \times_{\text{Id}} S^1$ is cobordant to $*_{\text{p}} \times_g S^1 = \emptyset$

$$\begin{array}{ccc} \text{"} & & \text{"} \\ * & \xleftarrow{\text{cobordant}} & \emptyset \\ \hookrightarrow // \leftarrow & & \end{array}$$

SAME HOLDS FOR ANY COMPACT MANIFOLD ! $\longrightarrow \blacktriangle$

WEIERSTRASS APPROXIMATION: Any continuous function $f: [0, 1] \rightarrow \mathbb{R}$ can be approximated by polynomials in the sup norm $\|f\|_{\infty} = \sup_{x \in [0, 1]} |f(x)|.$

(Generalize

STONE - WEIERSTRASS: for any compact Hausdorff top. space X (e.g., compact mfd's), if $A \subset C^0(X, \mathbb{R})$ is a subalgebra s.t.

1. A separates pts
2. A contains at least one nonzero continuous function

Then A is dense in the sup norm.

$\longrightarrow$ Since we can approximate all homotopies by smooth homotopies, the example above gives us that

COMPACT MANIFOLDS ARE NOT CONTRACTIBLE !

Ex: $\mathbb{RP}^4 = (\mathbb{R}^5 \setminus \{0\})/\sim$. In $\mathbb{R}^5$, choose two hyperplanes H_1 and H_2 s.t. $H_1 \cap H_2$ (i.e., $H_1 + H_2 = \mathbb{R}^5$). Then

4-dim

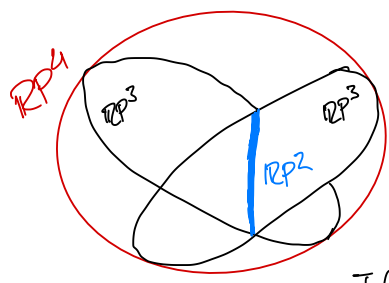
Projection

3-dim

$\mathbb{RP}^3 \simeq$

$\simeq \mathbb{RP}^3$

$$P(H_1) \cap P(H_2) = P(H_1 \cap H_2) \simeq \mathbb{RP}^2$$



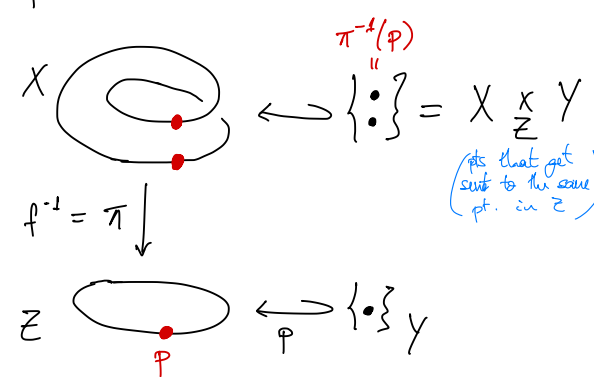
Q: Is it possible to remove intersection by deforming $2\mathbb{RP}^3$?

A: No! Since $\mathbb{RP}^2$ is not null-cobordant. If we remove this intersection, $\mathbb{RP}^2$ would be cobordant to $\emptyset$. Thom's classification of cobordism ring gives that $\mathbb{RP}^2$ is a generator in dim-2, hence cannot be null-cobordant.

Def: (DEGREE OF MAP) Let $f: M^d \rightarrow N^d$ be smooth and $\dim M = \dim N$ with M compact and N connected, then the degree of f is

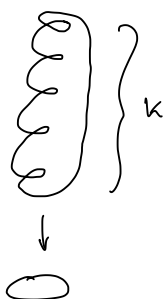
$$\deg_Z(f) := \pm_2(p, f),$$

$p \in N$

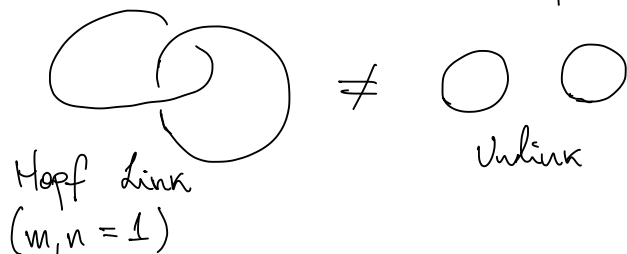


Ex: $f: S^1 \rightarrow S^1$ κ -fold cover
 $z \mapsto z^\kappa$

$$\deg_z f = \kappa \bmod 2.$$



Ex: Use intersection #/degree to study mufds that don't intersect. Say M^m, N^n are mufds of dim m, n and they sit inside $\mathbb{R}^{m+n+1}$. Example: 2 circles in $\mathbb{R}^3$



Q: Can we detect if mufds are linked or not?

Strategy: Convert this into an intersection problem in an auxiliary space. Define

$$\lambda: M \times N \longrightarrow S^{m+n} \quad \text{sphere at } \infty \text{ in } \mathbb{R}^{m+n}$$

$$(x, y) \longmapsto \frac{x-y}{\|x-y\|} \quad \begin{array}{l} \text{direction of } x \text{ from } y \\ \text{Will-def. b/c } M, N \text{ don't intersect} \end{array}$$

$\dim = m+n$ $\dim = m+n$

$\Rightarrow$ Can compute the degree of λ

For Hopf link, $\deg_z \lambda = 1$, $\lambda: S^1 \times S^1 \rightarrow S^2$

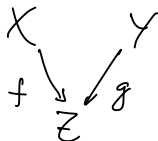


LECTURE 16

Nov 14th, 2024

SARD'S THEOREM: Transversality is generic.

Almost all pairs $(f, g) \in \text{Hom}(X, Z) \times \text{Hom}(Y, Z)$

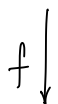


Rmk: Transversality may be expressed as the existence of regular value of a map.

$X, Y \subset Z$ submanifolds

$X \pitchfork Y \iff 0$ reg. value of $(f, g): Z \rightarrow \mathbb{R}^{\dim X + \dim Y}$

Ex: M



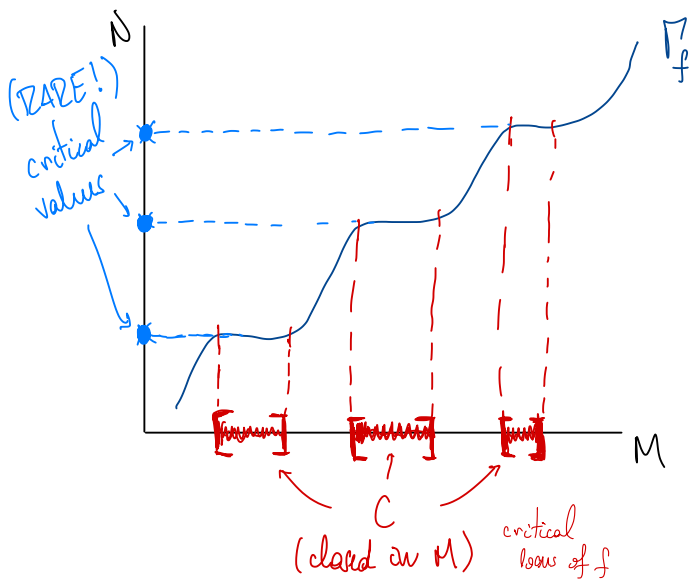
$N \xleftarrow{p \mapsto \nu_p} \{*\}$

$f: M \rightarrow N$

$p \in N$ is reg. value $\iff f \pitchfork p$.



Sard's Theorem: Let $f \in C^\infty(M, N)$ and let $C \subset M$ be the set of critical points of f . Then $f(C) \subset N$ has measure 0.



Remark: if f is not smooth, we need $f \in C^k(M, N)$ where $k > \dim M - \dim N + 1$

Def: A subset $X \subset M$ of a mfd M has measure 0 if, in each chart (U, φ) , $\varphi(X \cap U)$ has Lebesgue measure 0 in $\mathbb{R}^n$.

that's why we need mfd's to be 2nd countable...

i.e., $\forall \varepsilon > 0$, $\varphi(X \cap U)$ can be covered by a countable seq. of balls w/ total volume $< \varepsilon$.

Guarantees that the def. above is indep. of charts

Lemma: Let $I^m = [0, 1]^m$ and $f: I^m \rightarrow \mathbb{R}^n$ be C^1 .

(a) If $m < n$, then $f(I^m)$ has measure 0

(b) If $m = n$ and $A \subset I^m$ has measure 0 then $f(A)$ has measure zero

$A = I^m \times \{0\}$ $\xrightarrow{\pi} I^m$ $\xrightarrow{f} \mathbb{R}^n$

$I^m \times I^{n-m} \xrightarrow{\tilde{f}} \mathbb{R}^n$

$\xrightarrow{\pi} I^m \xrightarrow{f}$

$f(I^m) = \tilde{f}(A)$

Pf: (b) A meas. 0 $\Rightarrow \forall \varepsilon > 0 \exists$ seq. of balls B_k w/ radius r_k covering A s.t.

$$C_m \sum_{k \in \mathbb{N}} (r_k)^m < \varepsilon$$

Idea: Cover $f(A)$ w/ $f(B_k)$. So, find balls $B'_k \subset \mathbb{R}^n$ s.t. $f(B_k) \subset B'_k$ w/ $\sum_{k \in \mathbb{N}} \text{vol}(B'_k) < \varepsilon$.

Need: Estimate for expansion factor of f
If $f \in C^1(I^m, \mathbb{R}^n)$, I^m compact $\Rightarrow$ derivative is bounded

(LIPSCHITZ
CONSTANT
OF f)

$\nwarrow \exists K > 0$

$$\forall x, y \in I^m, \|f(x) - f(y)\| \leq K \|x - y\|.$$

$\Rightarrow f(A)$ covered by balls of radius $K r_k$

$$\Rightarrow \text{volume} \leq C_m \sum_k (K r_k)^m < K^m \varepsilon$$

$\Rightarrow$ $\varepsilon \searrow 0$
 $\downarrow$
0

$\Rightarrow f(A)$ is measure zero.

Corollary: 1) $f: M \rightarrow N$ C^1 $\dim M = \dim N$

then A meas. zero $\Rightarrow f(A)$ meas. zero

(uses 2nd count.)

2) (Baby Sard) If $\dim M < \dim N$, $C = \text{crit. pts.} = M$, $f \in C^1$
then $f(C) = f(M) \subset N$ has meas. zero (uses 2nd countable)

Thm: (Equidimensional Sard) $f: M \rightarrow N$ C^1
 $\dim M = \dim N$, $C = \text{crit. pts. of } f \subset M$, $f(C) \subset N$
 has meas. zero.

PF: Suffices to prove for $I^n \rightarrow \mathbb{R}^n$.

(1) Let K be the Lipschitz const. of f

$$\|f(x) - f(y)\| \leq K \|x - y\|.$$

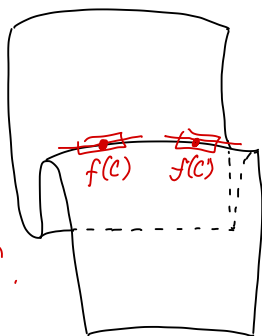
(2) Critical Vol. Comparison: $c \in I^n$ critical $\Rightarrow \text{im } Df_c$ is

critical locus



$\mathbb{R}^2$

Comparison of volume
along critical pts of f .



proper subspace
of $\mathbb{R}^n$.

Choose hyperplane
 H_c tangent at
 $f(c)$ containing
image.

Then $d(f(x), H_c) \leq \|f(x) - f_c^{\text{lin}}(x)\|$,
 where $f_c^{\text{lin}}(x) = f(c) + D_c f(x - c)$

By def. of derivative: $\forall \varepsilon > 0 \exists \delta > 0$ s.t.

$$\|f(x) - f_c^{\text{lin}}(x)\| < \varepsilon \|x - c\| \quad \forall x \text{ s.t. } \|x - c\| < \delta$$

Use I^n compact $f \in C^1 \Rightarrow$ unif δ in c for any ε
 $\uparrow$
 δ indep. of c

Combining (1) + (2): $\|x - c\| < \delta \Rightarrow f(x)$ is within $\varepsilon\delta$ of H_c .

$$d(f(x), H_c) \leq \|f(x) - f_c^{\text{lin}}(x)\| < \varepsilon \|x - c\| < \varepsilon\delta.$$

and within $\kappa\delta$ of $f(c)$

$\Rightarrow f(x)$ lies in a parallelepiped of volume $(2\varepsilon\delta)(2\kappa\delta)^{n-1}$

Finally: Need to cover crit. locus C w/ countably many balls/cubes st. we can use above est. in each one.

Easy: Subdivide cube into N^n small boxes st.

$$\text{diam}(\text{small cubes}) < \delta \quad \text{i.e., } \sqrt{n} \frac{1}{N} < \delta$$

$\Rightarrow$ covered critical locus of f w/ boxes of diam $< \delta$.

So,

$$\begin{aligned} \text{vol}(f(\text{small cubes} \cap C)) &\leq \left(2\varepsilon \frac{\sqrt{n}}{N}\right) \left(2\kappa \frac{\sqrt{n}}{N}\right)^{n-1} N^n \\ &= (2\varepsilon \sqrt{n})(2\kappa \sqrt{n})^{n-1} \xrightarrow{\varepsilon \rightarrow 0} 0. \end{aligned}$$



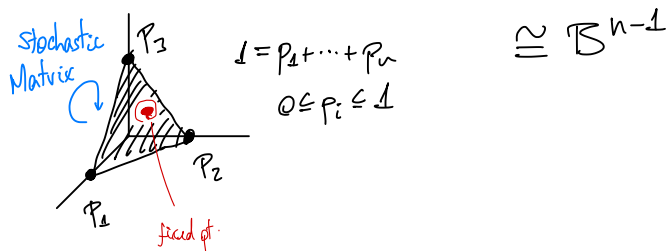
LECTURE 17

Nov 15th, 2024

* APPLICATIONS OF SARD:

Thm: (Brouwer Fixed Point) Any continuous map $f: \mathbb{B}^n \rightarrow \mathbb{B}^n$, $\mathbb{B}^n = \{x \in \mathbb{R}^n : \|x\| \leq 1\}$ has a fixed point.
 ↖ Manifold w/ boundary

Exmp: Space of prob. distrib. on n outcomes $\{1, 2, \dots, n\}$ is an n -simplex $\Delta^{n-1} = \{(p_1, \dots, p_n) : \sum p_i = 1, 0 \leq p_i \leq 1\}$



$$\cong \mathbb{B}^{n-1}$$

Lemma: Let M be a compact mfd w/ bdy. There is no smooth retract to ∂M ; i.e., there are no $f: M \rightarrow \partial M$ s.t. $f|_{\partial M} = \text{Id}_{\partial M}$.

Regular Value Thm. for mfds w/ bdy: $q \in N$ is reg. val.

$M \not\parallel \parallel \parallel \parallel$ of f and $\partial f \Rightarrow f^{-1}(q)$ is a submanifold w/ bdy given by

$$\partial f^{-1}(q) = f^{-1}(q) \cap \partial M$$



Pf: (Lemma) By contradiction assume such f exists.

By Sard's Thm, $\exists$ a reg. value $q \in \partial M$ for f
(since $f|_{\partial M} = \text{Id}_{\partial M}$ q is also reg. val. for ∂f)

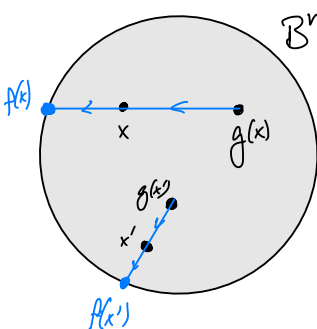
$\Rightarrow f^{-1}(q)$ is a submanifold w/ bdy of B^n s.t. single point
 $\partial(f^{-1}(q)) = f^{-1}(q) \cap \partial B^n = f^{-1}(q) \cap S^{n-1} = \{*\}$

But $\dim f^{-1}(q) = 1 \Rightarrow$ we built a compact 1-dim
manifold w/ bdy $\cong \{q\} \hookrightarrow \ll \Leftarrow$

□

Smooth Brouwer Fixed Pt. Thm: $\forall g \in C^0(B^n, B^n), \exists p, g(p) = p$

Pf: Contradiction: suppose g has no fixed points.



Extend the line $g(x) \mapsto x$ to ∂B^n
and obtain

$$f: x \mapsto \overline{g(x)x} \cap \partial B^n$$

which is a smooth retraction. $\hookrightarrow \ll \Leftarrow$

$$f(x) = x + tu \text{ where } u = \frac{x - g(x)}{\|x - g(x)\|}$$

$t =$ positive solution to a quadratic eq.
w/ positive discriminant.

since g is smooth
and f is given by
this smooth formula
 f is smooth

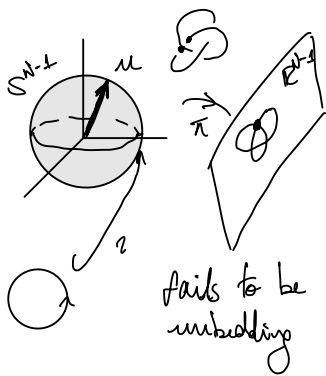
□

Pf: (BPT) Weierstrass approx. of continuous $B^n \ni$ by smooth maps, scaled slightly to fit in B^n . □

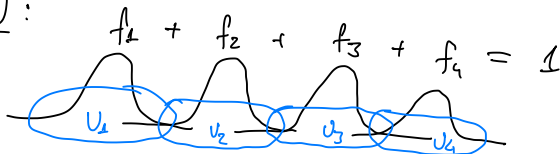
APPLICATION OF SARD:

Thm: (Whitney Embedding Theorem) Any n -manifold can embed in $\mathbb{R}^{2n+1}$.

Idea of Pf: Construct N w/ partition of unity and get the dimensions down by studying when projections fail to give embeddings.



POU:



Thm: (Partitions of Unity) Given a regular covering of M $\{(U_i, \varphi_i)\}$, $\exists \{f_i\}$ partition of unity subordinate to this covering st. $f_i > 0$ on $V_i \subset \varphi_i^{-1}(B_0(1))$ and $\text{supp } f_i \subset \varphi_i^{-1}(\overline{B_0(2)})$.

Def: A regular covering is a ^{locally finite (i.e., each $x \in M$ subseqd)} open cover $\{(U_i, \varphi_i)\}$ of M by coord. charts st. $\varphi_i(U_i) = B_0(3)$ and $V_i = \varphi_i^{-1}(B_0(1))$ also form a covering.

Def: A POU subordinate to cover $\{(U_i, \varphi_i)\}$ is a collection $(f_i: M \xrightarrow{C^\infty} [0,1])$ s.t. (1) $\text{Supp } f_i = \overline{f_i^{-1}(\{0\})} \subset \varphi_i^{-1}(B_0(2))$

only makes sense in the loc. finite case $\rightarrow$ since only finitely many f_i 's are $\neq 0$

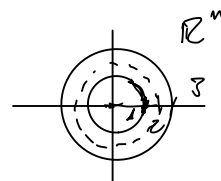
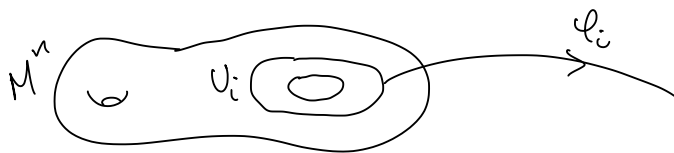
(2) $\sum_{i=1}^n f_i(x) = 1 \quad \forall x \in M$

LECTURE 18

Nov 21st, 2024

* WHITNEY EMBEDDING: Let M^n be compact mfd. ^{same idea for non-compact but more bookkeeping.}

Idea: Start w/ POU.:



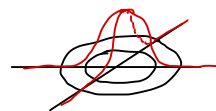
Adapted
POU

f_i

Regular covering of M^n :

$$\bigcup_i U_i \rightarrow \bigcup_i B_0(3)$$

$$\bigcup_i V_i \rightarrow \bigcup_i B_0(1)$$



1. Extend charts $\bigcup_{i \in M} U_i \xrightarrow{\varphi_i} \mathbb{R}^n$ to maps $M \rightarrow \mathbb{R}^n$ by doing
- $$f_i \varphi_i := \begin{cases} f_i \varphi_i, & \text{for } x \in U_i \\ 0, & \text{else} \end{cases}$$

This map is going to be an embed. on U_i but not anywhere else.

2. If we exit U_i and enter U_j , pass before to $f_j \varphi_j$.
 i.e.: for a covering $\{U_i\}_{i=1}^N$, define

$$\begin{aligned} M &\longrightarrow \mathbb{R}_1^n \times \mathbb{R}_2^n \times \dots \times \mathbb{R}_N^n \\ x &\longmapsto (f_1 \varphi_1(x), f_2 \varphi_2(x), \dots, f_N \varphi_N(x)) \end{aligned}$$

3. But to make this into an embedding, we need more information: define $\Phi: M \rightarrow (\mathbb{R}^n)^N \times \mathbb{R}^N = \mathbb{R}^{N(n+1)}$

$$\Phi(x) := (f_1 \varphi_1(x), \dots, f_N \varphi_N(x), \underbrace{f_1(x), \dots, f_N(x)}_{\text{bookkeeping information}})$$

bookkeeping information
to trace in which open
set x lives in.

Claim: Φ is injective

Pf: If $\Phi(x) = \Phi(y) \Rightarrow$ for some i , $f_i(x) = f_i(y) \neq 0$
 $\Rightarrow x, y \in U_i$ and $f_i \varphi_i(x) = f_i \varphi_i(y)$
 $\Rightarrow x = y$ b/c φ_i is injective (coord. map) $\square$

Claim: Φ is an immersion

Pf: Check $D\Phi: T_p M \rightarrow \mathbb{R}^{N(n+1)}$ is injective

$$D_x \Phi(v) = \left(D_x f_1(v) \varphi_1(x) + f_1(x) D_x \varphi_1(x), \dots, D_x f_r(v), \dots \right)$$

If $D_x \Phi(v) = 0$, must have $D_x f_i(v) = 0 \ \forall i$. Plugging this into the first part $\Rightarrow f_i(x) D_x \varphi_i(v) = 0 \ \forall i$

$\Rightarrow$ for some i , $f_i(x) \neq 0 \ x \in U_i$

$$\Rightarrow D_x \varphi_i(v) = 0 \Rightarrow v = 0$$

$\uparrow$
 φ_i coord. charts

□

Claim: Φ embedding

Pf: Φ injective immersion.

Φ homeo. b/c it's injective on a compact Hausdorff space.

□

Upshot: Can embed $\mathbb{RP}^2 \xrightarrow{\text{emb.}} \mathbb{R}^9 \leftarrow \begin{matrix} \text{as above} \\ (2+1) \cdot (2+1) \\ \text{\# of charts on atlas for } \mathbb{RP}^2 \end{matrix}$

Actually can reduce $\mathbb{RP}^2 \xrightarrow{\text{emb.}} \mathbb{R}^5$

$\xrightarrow{\text{Surgery theory}} \mathbb{R}^4$

Thm: Any manifold M embeds into $\mathbb{R}^{2 \dim M + 1}$ (actually $\mathbb{R}^{2 \dim M}$)

Pf: Here, assume M is compact (see notes for generalization)

Strategy: 1. Embed $M \hookrightarrow \mathbb{R}^N$ using previous result

2. Show that, if $N > 2\dim M + 1$, $\exists$ directions $u \in S^{N-1}$ s.t. projections to $\perp u$ is an embedding. Use Sard's Thm to show that the bad directions are measure 0.

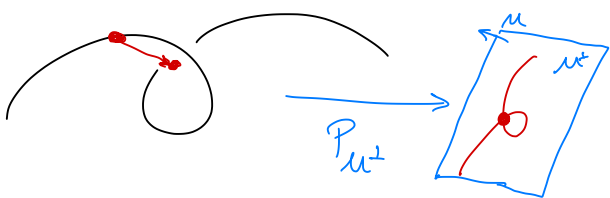
Q: What makes a direction bad?

(i) Failure of injectivity of $P_{u^\perp} \circ \Phi : M \rightarrow \mathbb{R}^{N-1}$

(ii) Failure of injectivity of the derivative

WTS: Both these failures only occur on sets of measure 0 in the sphere S^{N-1} .

(i) This failure occurs when $\exists (x, y) \in \overbrace{M \times M \setminus \Delta}^{(2n)\text{-dim manifold}}$ s.t.



$$\frac{\Phi(y) - \Phi(x)}{\|\Phi(y) - \Phi(x)\|} = u$$

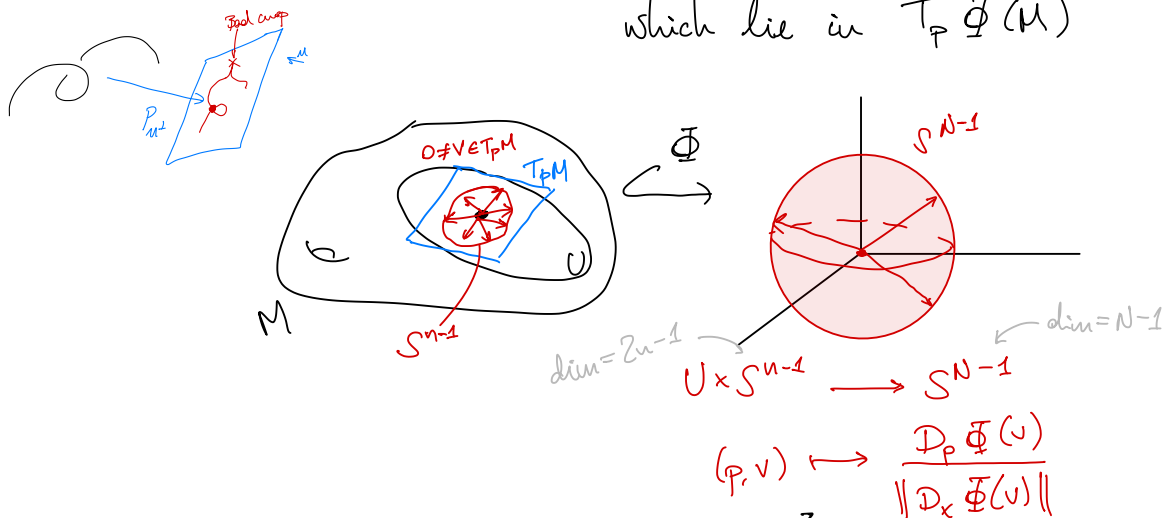
i.e.: $P_{u^\perp} \circ \Phi$ fails injectivity when $u \in S^{N-1}$ is in the image of the map:

$$\begin{aligned} \xrightarrow{2n \text{ dim}} M \times M \setminus \Delta &\longrightarrow S^{N-1} \xleftarrow{N-1 \text{ dim}} \\ (x, y) &\longmapsto \frac{\Phi(y) - \Phi(x)}{\|\Phi(y) - \Phi(x)\|} \end{aligned}$$

Sard: Image has measure of $2n < N-1$

$\Rightarrow$ Embedding into $N = 2n+1$ is the best we can do here.

(ii) Failure of injectivity of $D(P_{n+1} \circ \Phi)$ occurs for $u \in S^{N-1}$ which lie in $T_p \Phi(M)$



Immersion fails on image of this $\rightarrow$

Sard: immersion fails on a measure zero set if

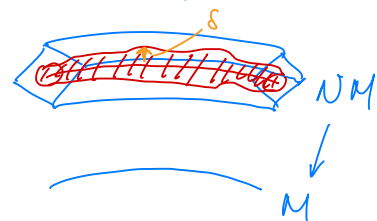
$$2n - 1 < N - 1; \text{ i.e., } 2n < N$$

Upshot: $\begin{cases} \text{Embed into } \mathbb{R}^{2\dim M + 1} \\ \text{Immersion into } \mathbb{R}^{2\dim M} \end{cases}$

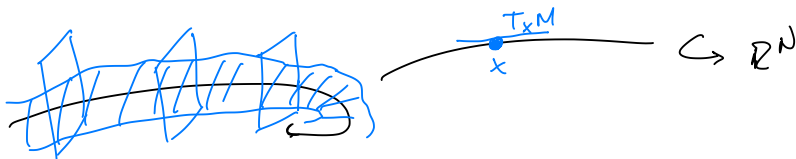
* TUBULAR NEIGHBORHOODS (for embeddings $M \hookrightarrow \mathbb{R}^N$)

Thm: Every submanifold M of $\mathbb{R}^N$ has a tubular nbhd.
i.e., U open nbhd of M which is diffeom. to the

ing of a solid cylinder in NM (normal bundle)

- Each point $x \in M$ has a normal space $N_x = \mathbb{R}^N / T_x M = T_x M^\perp$
 $\Rightarrow$ Form a vector bundle NM called the NORMAL BUNDLE


- Solid cylinder: Given $\delta: M \rightarrow \mathbb{R}_{>0}$
 $V = \{ (v, y) \in NM : \|v\| < \delta \}$



Map $V \rightarrow \mathbb{R}^N$
 $(y, v) \mapsto \Phi(y) + v$

Since $V \cong$ cylinder

$$V \xrightarrow[\text{retraction}]{r} M \quad V \xleftarrow[\text{inclusion}]{i} M$$

$$(y, v) \mapsto y \quad (y, 0) \longleftarrow y$$

$$r \circ i = \text{Id}_M$$

IMPORTANCE OF THIS:

* $f: M \rightarrow N$ may not be transverse to $g: K \rightarrow N$.

To modify f into a map which is transverse to g ,
 need to put f in a family of maps

largest space of functions not enough for $\mathcal{A}$, but we can add more directions by

$$F: \underbrace{M \times S}_{M \times \text{hom}} \rightarrow N \quad \text{s.t.} \quad F|_M : M \rightarrow N = f$$

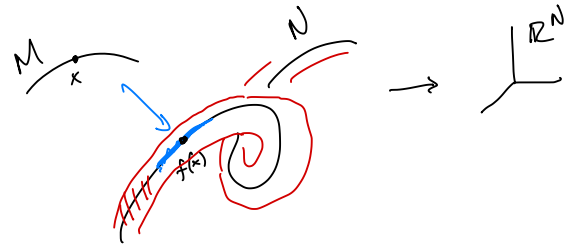
$s_0 \in S$ and $F \pitchfork g$. $\Rightarrow$ $\exists s \in S$ for which $f_s \pitchfork g$.

Q: How to deform f in this family $F: M \times S \rightarrow N$ to make it

transverse to g ?

A: Given $f: M \rightarrow N$, embed N in $\mathbb{R}^k$

$$M \longrightarrow N \hookrightarrow \mathbb{R}^k$$



$S = B^k$ open ball in $\mathbb{R}^k$
 use this to translate
 $F(x, s) = v(f(x) + s)$
 retraction of tubular nbhd

LECTURE 19

Nov 22nd, 2024

* VECTOR BUNDLES ($\subseteq$ Fiber bundles)

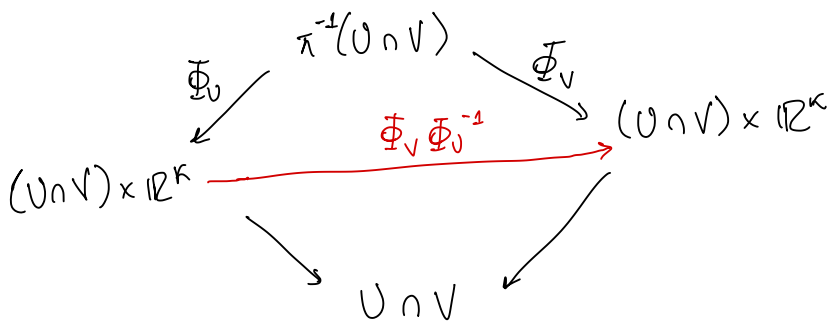
Def: E
 $\pi \downarrow$
 M

$\pi =$ bundle projection surjective
 s.t. $\forall p \in M \exists$ nbhd U and Φ homeo s.t. the

$$\begin{array}{ccc} \pi^{-1}(U) & \xrightarrow{\Phi} & U \times \mathbb{R}^k \\ \pi \searrow & \circlearrowleft & \swarrow \pi_1 \\ & U & \end{array}$$

diagram commutes

Overlap: if U, V are such nbhds w/ Φ_U, Φ_V resp. Then



$\Phi_V \Phi_U^{-1}$ = "transition function" : $U \cap V \xrightarrow{C^\infty} GL(k, \mathbb{R})$

Construction: To build a vector bundle over M

1. Build M from opens $\{U_i \subset \mathbb{R}^n\}$ via φ_{ij} gluing maps $(U_i \xrightarrow{\varphi_{ij}} U_j)$ _{diff'o.}

2. Provide $g_{ij} : U_i \cap U_j \rightarrow GL(k, \mathbb{R})$ and define

$$E := \bigcup_{i \in I} (U_i \times \mathbb{R}^k) / \begin{matrix} (x, u) \sim (y, v) \\ y = \varphi_{ij}(x) \\ v = g_{ij}(x) u \end{matrix}$$

← Equiv. relation b/c we have $\varphi_{jk} \varphi_{ij} = \varphi_{ik}$ and

$$g_{jk} g_{ij} = g_{ik} \quad \uparrow$$

cocycle condition (nonabelian 1-cocycle)

Ex: $S^2 = U_0 \cup U_1$. A vector bundle over S^2



U_0 is obtained by choosing

$$g_{01} : U_0 \cap U_1 \rightarrow GL(2, \mathbb{R})$$

$$U_0 \cap U_1 = \mathbb{R}^2 \setminus \{0\} = \mathbb{C}^*$$



$$e.g.: g_{01}(z \in \mathbb{C}^*) = r^n \begin{pmatrix} \cos n\theta & -\sin n\theta \\ \sin n\theta & \cos n\theta \end{pmatrix} = [z^n]$$

n = # of times this * plane turns as it goes around

$$\cap GL(2, \mathbb{R})$$

$$\cap GL(1, \mathbb{C})$$

the intersection before it's identified w/ the bottom plane
 $\Rightarrow \mathbb{Z}$ -family of rank-2 vector bundles over S^2 .

Rank: FB vs. VB

• FB: fiber type F $U_i \cap U_j \xrightarrow{g_{ij}} \text{Homeo}(F)$

• VB: fiber type $\mathbb{R}^k$ $U_i \cap U_j \xrightarrow{g_{ij}} GL(k, \mathbb{R})$

Variants: • Affine bundle: fiber type $\mathbb{R}^k$ (as affine space)

$$U_i \cap U_j \xrightarrow{g_{ij}} \text{Aff}(\mathbb{R}^k) = GL(k, \mathbb{R}) \ltimes \mathbb{R}^k$$

Right

• Principal G-bundle: fiber type G Lie group viewed as a right G -space

$$U_i \cap U_j \xrightarrow{g_{ij}} G \text{ (acting on the left)}$$

* OPERATIONS ON VECTOR BUNDLES: "Any functor involving vec. spaces can be upgraded to $VB \rightarrow M$."

e.g.: Duals

V finite-dim. $\mathbb{R}$ -vec. space

V^* dual

$$V^* = \text{Hom}(V, \mathbb{R})$$

$$V \xrightarrow[\text{linear}]{f} W$$

$$V^* \xleftarrow{f^*} W^* \quad (\text{contravariant functor})$$

If E is built from $U_i \times \mathbb{R}^k$ and $g_{ij}: U_i \cap U_j \rightarrow GL(k, \mathbb{R})$
 $\pi \downarrow$ $\downarrow$
 M U_i
 Apply functor to

Inverse is
a conseq. of
the contra-
variance of
dual functor

$$U_i \times (\mathbb{R}^k)^* \xrightarrow{(g_{ij}^*)^{-1}} U_j \times (\mathbb{R}^k)^*$$

$\downarrow$
 $\downarrow$

U_i
 U_j

get

$$g_{ij} \longleftrightarrow E$$

$$(g_{ij}^*)^{-1} \longleftrightarrow E^*$$

dual VB

e.g.: Sum $V, W \mapsto V \oplus W$

$$\begin{array}{l}
 f: V \rightarrow V' \\
 g: W \rightarrow W'
 \end{array}
 \rightsquigarrow
 f \oplus g: V \oplus W \rightarrow V' \oplus W'$$

$$(v, w) \mapsto (f(v), g(w))$$

rank- k	rank- l
E	E
$\downarrow$	$\downarrow$
M	M
g_{ij}	h_{ij}
$U_i \rightarrow GL(k, \mathbb{R})$	$U_j \rightarrow GL(l, \mathbb{R})$

Direct sum VB

$$\begin{array}{c}
 E \oplus F \\
 \downarrow \\
 M
 \end{array}
 \quad \text{rank}-(k+l)$$

$$G_{ij} = \left(\begin{array}{c|c} \overset{k \times k}{g_{ij}} & 0 \\ \hline 0 & \underset{l \times l}{h_{ij}} \end{array} \right)$$

e.g.: Tensor product $V, W \mapsto V \otimes W$

$$f: V \rightarrow V \xrightarrow{\dim V = k} f \otimes g: V \otimes W \longrightarrow V \otimes W$$

$$g: W \rightarrow W \xrightarrow{\dim W = l} \sum_{i,j} v_i \otimes w_j \mapsto \sum_{i,j} f(v_i) \otimes g(w_j)$$

Bases $(e_i^V), (e_i^W)$

for V, W .



as matrices $f \otimes g$ "Kronecker product".

Basis for $V \otimes W$: $(e_1^V \otimes e_1^W, e_1^V \otimes e_2^W, \dots, e_1^V \otimes e_l^W, e_2^V \otimes e_1^W, \dots)$

$$\dim V \otimes W = (\dim V)(\dim W) = kl$$

$$\begin{array}{|c|} \hline f \\ \hline k \times k \\ \hline \end{array} \otimes \begin{array}{|c|} \hline g \\ \hline l \times l \\ \hline \end{array}$$

Kronecker
product
→

$$\left(\begin{array}{ccc} \boxed{\begin{array}{|c|} \hline 1 \times l \\ \hline gf_{11} \\ \hline \end{array}} & \boxed{gf_{12}} & \dots & \boxed{} \\ \boxed{gf_{21}} & \dots & & \\ \vdots & & & \end{array} \right)$$

* ASSOCIATED VB TO THE TANGENT BUNDLE

$M \subset \mathbb{C}^n$ manifold $\Rightarrow$ TM tangent bundle w/ transition fcts

$$U_i \times \mathbb{R}^n \longrightarrow U_j \times \mathbb{R}^n$$

$$(x, u) \longmapsto (\varphi_{ij}(x), D_x \varphi_{ij}(u))$$

TM has many associated VBs:

Ex: COTANGENT BUNDLE T^*M

$$g_{ij} = \left((D_x \varphi_{ij})^* \right)^{-1}$$

Element of T_x^*M is a linear fct on $T_x M$.

Ex: $\underbrace{TM \otimes \dots \otimes TM}_k \otimes \underbrace{T^*M \otimes \dots \otimes T^*M}_l \leftarrow \text{rank } n^{k+l}$

$$g_{ij} = (D_x \varphi_{ij}) \otimes \dots \otimes (D_x \varphi_{ij}) \otimes ((D_x \varphi_{ij})^*)^{-1} \otimes \dots \otimes ((D_x \varphi_{ij})^*)^{-1}$$

↑ This is the bundle of (k, l) -tensors k -covariant
 l -contravariant

Interpretation: $\omega \in T_x^*M \otimes T_x^*M$ is a bilinear fct. on $T_x M$

$$\underbrace{\wedge^2 T_x^*M}_{\text{skew-symmetric bilinear forms}} \oplus \underbrace{\text{Sym}^2 T_x^*M}_{\text{symmetric bilinear forms}}$$

Def: A section of VB $E \xrightarrow{\pi} M$ is a C^∞ map
 $s: M \rightarrow E$ s.t. $\pi s = \text{Id}_M$

e.g.: Riem. manifolds - M C^∞ manifold

- g sym. bilinear form, positive def. on each tangent space varying over M

$g \in C^\infty(M, \text{Sym}^2 T^*M) \longrightarrow g$ is a $(0,2)$ -tensor

$\text{Sym}^2 T^*M = \text{VB}$ of symmetric 2-tensors

$\cap$

$T^*M \otimes T^*M$

X, Y vec. fields $\Rightarrow g(X, Y) \in C^\infty(M, \mathbb{R})$

$$g(X, Y)_x = g_x(X_x, Y_x).$$

e.g.: Symplectic Manifold

- M C^∞ mfd

only possible when $\dim M = \text{even}$
 $\uparrow$

- $\omega \in C^\infty(M, \wedge^2 T^*M)$ nondegenerate skew-symmetric bilinear form on each tangent space (and $\text{med } d\omega = 0$).

e.g.: Complex Manifold

- M C^∞ mfd

- Complex structure on each tangent space. Need to define multiplication by i to define this structure:

$$I: T_x M \longrightarrow T_x M \quad \text{i.e., } I \in T_x^* M \otimes T_x M$$

$$I^2 = -\text{id}$$

$$\text{i.e., } I \in C^\infty(M, T^*M \otimes TM)$$

only possible when $\dim M = \text{even}$

$$\text{s.t. } I^2 = -\text{id}_{TM}.$$

(also need involutivity needed to get complex coordinates on $\mathbb{C}^n$)

Ex: • Tensor algebra

$$\dim \otimes^\bullet V = \infty$$

Non-commutative
↓

Tautological product:

$$(a_1 \otimes \dots \otimes a_k) \cdot (b_1 \otimes \dots \otimes b_\ell) = a_1 \otimes \dots \otimes a_k \otimes b_1 \otimes \dots \otimes b_\ell$$

• Exterior algebra: $\wedge^\bullet V = \otimes^\bullet V / \langle x \otimes x : x \in V \rangle$

↑

i.e., expressions w/ $a \otimes a$
always get killed

$$(x+y) \otimes (x+y) = \cancel{x \otimes x}^{=0} + x \otimes y + y \otimes x + \cancel{y \otimes y}^{=0}$$

$$\Rightarrow x \otimes y = -y \otimes x$$

↓

That's why we call $\wedge^\bullet V$ a graded commutative algebra (b/c it's almost commutative except for a minus sign).

$$\dim V = n$$

$$\wedge^\bullet V = (\mathbb{R} = \wedge^0 V) \oplus \wedge^1 V \oplus \wedge^2 V \oplus \wedge^3 V \oplus \dots \oplus \wedge^n V \oplus 0 \oplus 0 \oplus \dots$$

$\underset{1}{\mathbb{R}}$ $\begin{matrix} e_1 \\ \vdots \\ e_n \end{matrix}$ $\begin{matrix} e_1 e_2 & \dots & e_1 e_j \dots e_k \\ e_1 e_3 & \dots & e_i e_j \dots e_k \end{matrix}$ $\begin{matrix} e_1 e_2 \dots e_n \\ \vdots \\ e_i e_j \dots e_k \end{matrix}$ $\begin{matrix} e_1 \dots e_n \\ \vdots \\ 1\text{-dim} \end{matrix}$

$$V = \mathbb{R}\text{-vec. space } \dim V = n$$

$$\otimes^\bullet V = \text{free algebra generated by } V \\ = (\mathbb{R} = \otimes^0 V) \oplus V \oplus (V \otimes V) \\ \oplus (V \otimes V \otimes V) \oplus \dots$$

$$\begin{array}{c}
 \vdots \\
 e_2 \wedge e_3 \\
 e_2 \wedge e_4 \\
 \vdots \\
 e_3 \wedge e_4 \\
 \vdots \\
 \downarrow \\
 e_i \wedge e_j \\
 i < j
 \end{array}$$

$$\dim \Lambda^\bullet V = 2^n$$

$\mathbb{Z}$ -Graded b/c $\Lambda^\bullet V = \bigoplus_{k \in \mathbb{Z}} \Lambda^k V$ and
commutative algebra $\alpha, \beta \text{ deg } k, l \rightarrow \text{deg } (k \wedge l) = k + l$

$$\alpha \wedge \beta = (-1)^{(\text{deg } \alpha)(\text{deg } \beta)} \beta \wedge \alpha$$

LECTURE 20

Nov 28th, 2024

* DIFFERENTIAL FORMS: M C^∞ mfd.

diff. k -forms

Differential graded commutative algebra: $\Omega^\bullet(M) = \bigoplus_{k \geq 0} \Omega^k(M)$

where $\Omega^k(M) = C^\infty(M, \Lambda^k T^*M)$.

The product in this algebra is the wedge product: $\alpha \wedge \beta$.

Note: $\alpha \wedge \beta = (-1)^{(\text{deg } \beta)(\text{deg } \alpha)} \beta \wedge \alpha$

non zero only for
 $k = 0, 1, \dots, \dim M$

* THE DIFFERENTIAL: In degree-0, we have (fct $M \rightarrow \mathbb{R}$)

$$\Omega^0(M) = C^\infty(M, \Lambda^0 T^*M) = C^\infty(M, \mathbb{R})$$

ψ

$$f: M \rightarrow \mathbb{R}$$

$$Df: TM \rightarrow T\mathbb{R} = \mathbb{R} \times \mathbb{R}$$

$$(x, v) \mapsto (f(x), \underbrace{D_x f(v)})$$

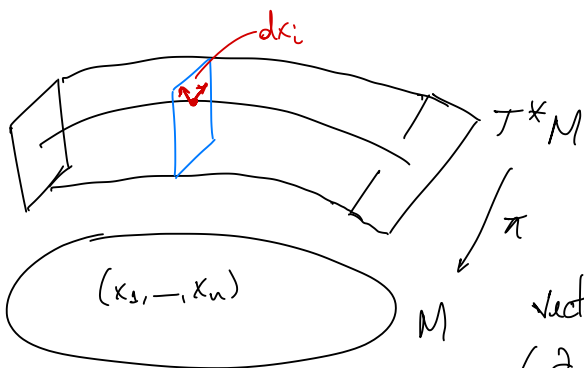
$v \mapsto D_x f(v)$ is a linear fct. on $T_x M$

Def: $\pi_2 \circ Df =: df$ is a smooth section of T^*M
i.e., $df \in \Omega^1(M) = C^\infty(M, \Lambda^1 T^*M)$.

$$\Omega^0(M) \xrightarrow{d} \Omega^1(M) \text{ de Rham operator (exterior derivative)}$$

In local coordinates: $(x_1, \dots, x_n)$ coords $(x_i: M \rightarrow \mathbb{R})$

have derivatives $(dx_1, \dots, dx_n)$, $dx_i \in \Omega^1(M)$.



For $f \in \Omega^0(M)$,

$$df = a_1 dx_1 + \dots + a_n dx_n,$$

$$a_i \in \Omega^0(M).$$

How to find these a_i ? Use vector fields! They have a basis $(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n})$ (sections of TM).

Duality pairing: $df\left(\frac{\partial}{\partial x_k}\right) = a_k$

$$\parallel$$
$$\frac{\partial f}{\partial x_k}$$



Upshot:

In coordinates, $df = \sum_{k=1}^n \left(\frac{\partial f}{\partial x_k}\right) dx_k$

Cor: $df=0 \Rightarrow f$ is constant on each connected component of M .

↓ From this, can define the general exterior derivative.

Def: $d: \Omega^{\bullet}(M) \rightarrow \Omega^{\bullet}(M)$ is the unique ^① graded derivativisation of $\deg+1$ st. df is as above ^② (i.e., $df(X) = X(f)$ ^③) for $f \in \Omega^0(M)$; and $d(df) = 0$ $\forall f \in \Omega^0(M)$.

$$0 \xrightarrow{d} \Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \Omega^2(M) \xrightarrow{d} \dots \xrightarrow{d} \Omega^n(M) \xrightarrow{d} 0$$

Graded Derivation: Leibniz rule degree $d = +1$ always

$$d(\alpha \wedge \beta) = (d\alpha) \wedge \beta + (-1)^{|\alpha|} \alpha \wedge (d\beta)$$



To show this exists, we can explicitly compute it in coordinates: let $\rho = \sum_{k=1}^n \xi_k dx_k \in \Omega^1(M)$, $\xi_k \in \Omega^0(M)$.

Then

$$\begin{aligned} d\rho &= d\left(\sum_{k=1}^n \xi_k dx_k\right) \\ &= \sum_{k=1}^n \left((d\xi_k) \wedge dx_k + \overset{\substack{\text{differential} = (-1)^{1-0} = +1 \\ \downarrow}}{(-1)} \xi_k d(dx_k) \right) \\ &= \sum_{k=1}^n \left(\sum_{j=1}^n \frac{\partial \xi_k}{\partial x_j} dx_j \right) \wedge dx_k \end{aligned}$$

$$d\rho = \sum_{j < k} \left(\frac{\partial \xi_k}{\partial x_j} - \frac{\partial \xi_j}{\partial x_k} \right) dx_j \wedge dx_k$$

Now, take a general k -form $\rho \in \Omega^k(U)$, where the coords. in U are $(x_1, \dots, x_n)$. Then we can write

$$\rho = \sum_{i_1 < i_2 < \dots < i_k} \rho_{i_1, \dots, i_k}^{\in \Omega^k(M)} dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

$$(*) \quad d\rho = \sum_{l=1}^n \left(\sum_{i_1 < \dots < i_k} \frac{\partial \rho_{i_1, \dots, i_k}}{\partial x_l} dx_l \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k} \right) \in \Omega^{k+1}(M)$$

In order for the def. of $d: \Omega^*(M) \rightarrow \Omega^*(M)$ to be well-defined, we need to check that the proposed operator (*) satisfies ① + ② + ③.

② Clear

$$\begin{aligned}
 \textcircled{3} \quad d(df) &= d\left(\sum_k \frac{\partial f}{\partial x_k} dx_k\right) = \sum_k \left(d\left(\frac{\partial f}{\partial x_k} dx_k\right)\right) \\
 &= \sum_k \left(d\left(\frac{\partial f}{\partial x_k}\right) \wedge dx_k + \overset{\substack{+0 = (-1) \\ (-1)}}{\left(\frac{\partial f}{\partial x_k}\right)} \wedge \cancel{d(dx_k)}^{\substack{+0 \\ =0}}\right) \\
 &= \sum_k \sum_l \frac{\partial^2 f}{\partial x_k \partial x_l} dx_l \wedge dx_k \\
 &= \sum_{k < l} \left(\frac{\partial^2 f}{\partial x_k \partial x_l} - \frac{\partial^2 f}{\partial x_l \partial x_k}\right) dx_k \wedge dx_l = 0.
 \end{aligned}$$

① For $f, g \in \Omega^0(M)$,

$$d\left((f dx_{i_1} \wedge \dots \wedge dx_{i_p}) \wedge (g dx_{j_1} \wedge \dots \wedge dx_{j_q})\right)$$

$$= d(fg dx_{i_1} \wedge \dots \wedge dx_{i_p} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_q})$$

use fact: $d(fg) = (df)g + f(dg)$ (old Leibniz rule)

$$\begin{aligned}
&= f dg \wedge dx_{i_1} \wedge \dots \wedge dx_{i_p} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_q} \\
&\quad + g df \wedge dx_{i_1} \wedge \dots \wedge dx_{i_p} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_q} \\
&= d(f dx_{i_1} \dots dx_{i_p}) \wedge g dx_{j_1} \dots dx_{j_q} \\
&\quad + (-1)^p f dx_{i_1} \dots dx_{i_p} \wedge d(g dx_{j_1} \dots dx_{j_q})
\end{aligned}$$

Thm: $d^2 = 0$.

Pf: d graded derivation $\Rightarrow d \in \text{Der}^1(\Omega^\bullet, \wedge)$.

graded Derivations are closed under *graded* commutator (i.e., they form a *graded* Lie algebra).

$$D_1 \in \text{Der}^{d_1}, D_2 \in \text{Der}^{d_2}$$

$$[D_1, D_2] := D_1 \circ D_2 - (-1)^{d_1 d_2} D_2 \circ D_1 \quad (\text{Graded Commutator})$$

Exercise: $[D_1, D_2] \in \text{Der}^{d_1+d_2}$.

$$\begin{aligned}
\text{Pf: Take } \alpha, \beta, \quad [D_1, D_2](\alpha \wedge \beta) &= D_1 \underbrace{D_2(\alpha \wedge \beta)}_{\text{Liebriz}} - (-1)^{d_1 d_2} D_2 \underbrace{D_1(\alpha \wedge \beta)}_{\text{Liebriz etc...}}
\end{aligned}$$

□

$$[d, d] = d \circ d - (-1)^{1 \cdot 1} d \circ d = 2d^2$$

$\Rightarrow d^2$ is a graded derivation of degree 2.

$\Rightarrow$ Suffices to check

$d^2 = 0$ on forms of type

$$f \in \Omega^0$$

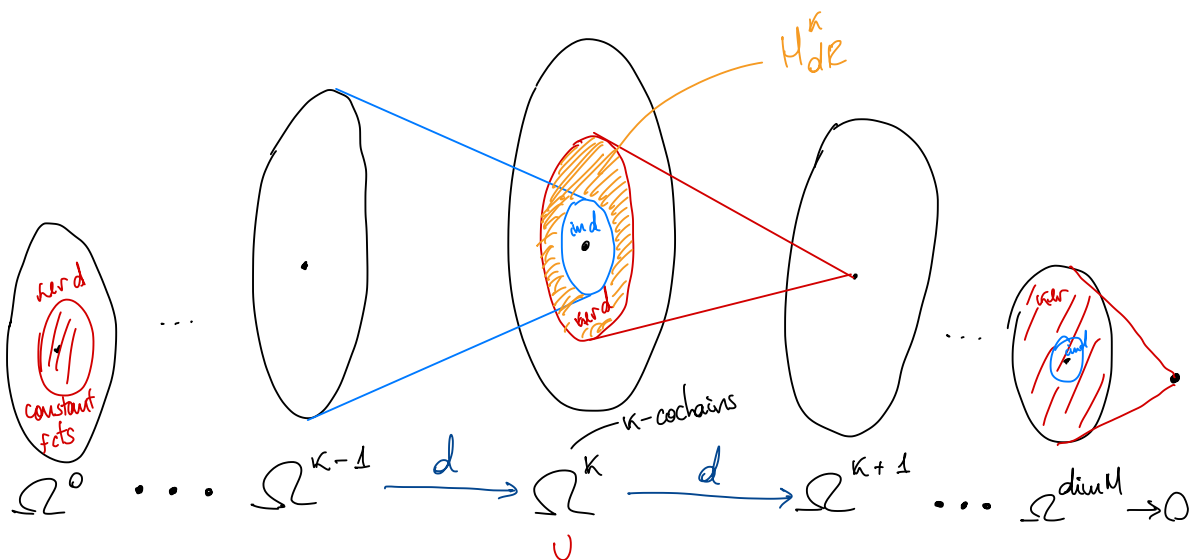
$$dg, g \in \Omega^0.$$

local generators for Ω^0 .

But $d^2 f = 0$ by def. (*)

$$d^2(dg) = d(d^2 g) = d(0) = 0.$$

CONSEQUENCE OF $d^2 = 0$: $\text{im } d \subset \text{ker } d$ b/c $d^2 = 0$



dual terminology
to ∂ boundary for
mflds, and sing. homology

$$(\text{ker } d) \cap \Omega^k = \kappa\text{-cocycles}$$

$$(\text{ind}) \cap \Omega^k = \kappa\text{-coboundaries}$$

Leads to definition

Def: The de Rham cohomology is the graded algebra given by

$$H_{dR}^\bullet(M) := \bigoplus_{k=0}^{\dim M} \underbrace{\left(\ker d \cap \Omega^k / \operatorname{im} d \cap \Omega^k \right)}_{\parallel H_{dR}^k(M)}$$

Topological invariant of spaces.

LECTURE 21

Nov 29th, 2024

Differential forms: $\rho \in \Omega^k(M)$ can be written locally as

$$\rho|_{\text{loc}} = \sum p_{i_1, \dots, i_k} dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

$M \rightsquigarrow$ diff. commutative graded algebra $(\Omega^\bullet(M), \wedge, d)$

$M \rightarrow C^\infty(M, \mathbb{R})$ comm. alg.

Pull-back: $N \hookrightarrow C^\infty(N, \mathbb{R})$
 $F \uparrow \quad \quad \downarrow F^*$
 $M \hookrightarrow C^\infty(M, \mathbb{R})$

$$\begin{array}{ccc} \mathbb{R} & & \mathbb{R} \\ \uparrow & & \uparrow + \\ M & \xrightarrow{F} & N \\ C^\infty(M, \mathbb{R}) & \xleftarrow{F^*} & C^\infty(N, \mathbb{R}) \end{array}$$

$$\begin{array}{ccc}
 \Lambda^k T^*M & \longleftarrow & \Lambda^k T^*N \\
 \downarrow & & \downarrow \\
 M & \xrightarrow{F} & N
 \end{array}$$

F^*p
 pullback of p

$p \in \Omega^k(N)$

$$\begin{array}{ccc}
 TM & \xrightarrow{DF} & TN \\
 T^*M & \xleftarrow{DF^*} & T^*N
 \end{array}$$

So, transform manifolds into this algebraic object

$$\begin{array}{ccc}
 N & & (\Omega^k(N), \wedge, d) \\
 F \uparrow & \xrightarrow[\text{functor}]{\Omega} & \downarrow F^* \text{ morphism of cdga} \\
 M & & (\Omega^k(M), \wedge, d)
 \end{array}$$

In local coordinates:

$$\begin{array}{ccc}
 M & \xrightarrow{F} & N \rightarrow \mathbb{R} \\
 x_i & & y_j
 \end{array}$$

$y = y(x)$
 basis dy_i for $\Omega^1(N)$

$$F^* dy_i = \sum_{j=1}^n \underbrace{\frac{\partial F_i}{\partial x_j}}_{\substack{\text{entries of Jacobian of } F \\ \text{(i.e., of } DF)}; F_i = y_i \circ F} dx_j$$

So, for $p \in \Omega^k(N)$,

$$F^*(\rho_{i_1 \dots i_k}(y) dy_{j_1} \wedge \dots \wedge dy_{j_k})$$

$$= (\rho_{j_1 \dots j_k} \circ F)(x) \sum_{i_1} \dots \sum_{i_k} \left(\frac{\partial y_{j_1}}{\partial x_{i_1}} \dots \frac{\partial y_{j_k}}{\partial x_{i_k}} \right) dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

$$= \sum_{i_1 < \dots < i_k} \left(\begin{matrix} k \times k \text{ minor} \\ \text{of } DF \end{matrix} \right) dx_{i_1} \wedge \dots \wedge dx_{i_k}$$

$dy_{j_1} = \frac{\partial y_{j_1}}{\partial x_1} dx_1 + \dots + \frac{\partial y_{j_1}}{\partial x_n} dx_n$
 $\vdots$
 $dy_{j_k} = \frac{\partial y_{j_k}}{\partial x_1} dx_1 + \dots + \frac{\partial y_{j_k}}{\partial x_n} dx_n$

Remark: If F is a diffeo, DF is $n \times n$, then

$$F^*(\overset{\text{top degree}}{dy_1} \wedge \dots \wedge \overset{\text{dy}_i/\partial x_i}{dy_n}) = (\det DF) dx_1 \wedge \dots \wedge dx_n.$$

Jacobian determinant

$\hookrightarrow$ Integration is well-defined on manifolds!

Recall: Change of Variables Formula

$$\int f(y) dy_1 \dots dy_n \stackrel{y=y(x)}{=} \int f(y(x)) \left| \det \frac{\partial y_i}{\partial x_j} \right| dx_1 \dots dx_n.$$

For these 2 formulas to agree, need F to "preserve orientation" i.e., need $\det DF > 0$.

}

Def: Let M be an n -dim. mfd.. It is orientable when the line bundle $\wedge^n T^*M \simeq M \times \mathbb{R}$.

An orientation is an equivalence class of nonvanishing sections $v \in \Omega^n(M)$ where $v' \sim v$ if $v' = e^f v$, for $f \in C^\infty(M, \mathbb{R})$.
positive function

M is oriented when it's endowed w/ orientation $(M, [v])$.

Cor: If M is oriented, we can cover M with charts U_i s.t. the gluing maps φ_{ij} have positive Jac. det..

Pf: For each chart $\varphi_i: U_i \rightarrow \mathbb{R}^n$

$\varphi_i^*(dx_1 \wedge \dots \wedge dx_n)$ — if this is in $[v]$ OK ✓
— if this is in $[-v]$, change the sign of first entry of φ_i :

$$\begin{pmatrix} -1 & & & 0 \\ & 1 & & \\ & & \ddots & \\ 0 & & & -1 \end{pmatrix} \circ \varphi_i.$$

Upshot: For M oriented, have a well-defined INTEGRAL

Def: Let $(M, [v])$ be an oriented n -mfd. The integral is the unique linear map $\int: \Omega_c^n(M) \rightarrow \mathbb{R}$ s.t. it is compatible with the usual Lebesgue integral in $\mathbb{R}^n$
compact supported forms
i.e., if $h: V \subset \mathbb{R}^n \xrightarrow{\text{diffeo}} U \subset M$ is orientation preserving

ving (i.e., $h^*v \sim [dx_1, \dots, dx_n]$) and if $\alpha \in \Omega_c^n(M)$ with support in U , then $\int_M \alpha = \int_{\mathbb{R}^n} h^* \alpha$

* We cannot integrate functions on manifolds.
 We can only integrate top-degree forms

Pf: Idea: • Use property to write unique expression for $\int$
 • Prove it satisfies claim

If $\alpha \in \Omega_c^n(M)$ choose oriented atlas (U_i, φ_i)
 " P.O.U. φ_i subordinate to (U_i, φ_i)

$$\alpha = \left(\sum_i \varphi_i \right) \alpha = \sum_i \varphi_i \alpha$$

$$\int \alpha = \sum_i \int \varphi_i \alpha = \sum_i \int_{\varphi_i(U_i)} (\varphi_i^{-1})^* \varphi_i \alpha$$

Prove this satisfies the properties.

□

• Each nonvanishing element $v \in \Omega^n(M)$ defines a measure (or volume form) on M

$$\mathcal{Q}^0(M) \ni f \longmapsto \int_M f v \quad \text{makes sense}$$

e.g.: if a Riemannian metric is chosen on an oriented $M \Rightarrow$ obtain a canonical $v_g \in \Omega^n(M)$ "volume" measure (usually called vol)

STOKES' THEOREM: Let M be an n -mfd with boundary ∂M . Let $[v]$ be an orientation on M , which induces an orientation on ∂M using outward convention.

Let $\rho \in \Omega^{n-1}(M)$, then

$$\int_M d\rho = \int_{\partial M} \rho = \int_{\partial M} \tau_0^* \rho$$

More precise: $\tau_0: \partial M \hookrightarrow M$
submfd

RMK: This shows the duality between $d \leftrightarrow \partial$.

Cor 1: If $\partial M = \emptyset$, then $\int_M d\rho = 0 \quad \forall \rho \in \Omega^{n-1}(M)$.

Cor 2: If $\partial M = \emptyset$ and v is a volume form, $v \in \Omega^n(M)$, then, using orientation $[v]$, $\int_M v > 0$

$\Rightarrow v$ cannot be in the image of d

$\Rightarrow [v] \neq 0$ in $H_{dR}^n(M)$.

Philosophy: may think of $\Omega^k(M)$ as follows:

Ω^0 evaluate on points (functions on pts)

Ω^1 function on 1-dimension embedded submanifolds

e.g., 1-form on M can be pulled back to, say, a circle and we can integrate it there b/c, there, it's a top form



$\vdots$
 Ω^k functions on maps from k -dim. domains

$\vdots$
 Ω^n

* MAYER - VIÉTORIS: Method for computing $H_{dR}^i(M)$
(local-to-global)

Main Input $\begin{cases} \text{Partition of unity} \\ \text{Poincaré Lemma: } H_{dR}^k(\mathbb{R}^n) = \begin{cases} \mathbb{R}, & k=0 \\ 0, & \text{else} \end{cases} \end{cases}$

$k=0, H_{dR}^0(\mathbb{R}^n)$
is just const. fcts.
 $\mathbb{R}^n$ is connex

Lemma: If $f, g: M \rightarrow N$ are homotopic i.e., $\exists H: [0,1] \times M \rightarrow N$
then the pullback morphisms f^*, g^* are $H(0, -) = f, H(1, -) = g$
chain homotopic i.e., $\exists$ homotopy K between them

$$\begin{array}{ccccc}
 \Omega^{k-1}(M) & \xrightarrow{d} & \Omega^k(M) & \xrightarrow{d} & \Omega^{k+1}(M) \\
 \uparrow f^* & & \uparrow f^* & & \uparrow f^* \\
 \uparrow g^* & & \uparrow g^* & & \uparrow g^* \\
 \Omega^{k-1}(N) & \xrightarrow{d} & \Omega^k(N) & \xrightarrow{d} & \Omega^{k+1}(N)
 \end{array}$$

i.e., $K: \Omega^k(N) \rightarrow \Omega^{k+1}(M)$
(degree $K = -1$)
s.t.

$f^* - g^* = Kd + dK$

" $[K, d]$

e.g.: if $\alpha \in \Omega^k(N)$, $d\alpha = 0$, then $f^*\alpha, g^*\alpha$ are closed
 $d(f^*\alpha) = d(g^*\alpha) = 0$. But note:

$$(f^* - g^*)\alpha = (Kd + dK)\alpha = d(K\alpha)$$

$\Rightarrow f^* - g^*$ is exact

$$\Rightarrow [f^*\alpha] = [g^*\alpha] \text{ in } H_{dR}^k(M)$$

Cor: If f, g are homotopic $\Rightarrow$ induced maps f^*, g^* on $H_{dR}^\bullet$ agree

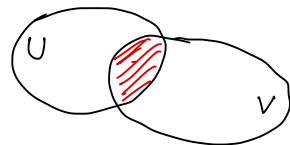
Cor: If M, N are homotopic $\Rightarrow H_{dR}^\bullet(M) \cong H_{dR}^\bullet(N)$.

$$\begin{array}{ccccc}
 M & \xrightarrow{\text{functor}} & (\Omega^\bullet(M), \wedge, d) & \xrightarrow{\text{functor}} & (H_{dR}^\bullet(M), \wedge) \\
 \text{mflds} & & \text{cdga} & & \text{cga}
 \end{array}$$

$d=0$ here $\downarrow$

MAYER - VIETORIS SEQUENCE: Suppose $M = U \cup V$ (e.g.: $S^n = U_N \cup U_S$)
 $\uparrow$ open sets

$$\begin{array}{ccc} U & \xleftarrow{\partial_U} & U \cap V \\ \downarrow \iota_U & & \downarrow \partial_V \\ M & \xleftarrow{\iota_V} & V \end{array}$$



Apply $\Omega^\bullet$

$$\begin{array}{ccc} \Omega^\bullet(U) & \xrightarrow{\partial_U^*} & \Omega^\bullet(U \cap V) \\ \uparrow \iota_U^* & & \uparrow \partial_V^* \\ \Omega^\bullet(M) & \xrightarrow{\iota_V^*} & \Omega^\bullet(V) \end{array}$$

$$0 \xrightarrow{\textcircled{1}} \Omega^\bullet(M) \xrightarrow{(\iota_U^*, \iota_V^*)} \Omega^\bullet(U) \oplus \Omega^\bullet(V) \xrightarrow{\partial_V^* - \partial_U^*} \Omega^\bullet(U \cap V) \xrightarrow{\textcircled{3}} 0$$

Note: 0. complex ($d^2 = 0$)

1. (ι_U^*, ι_V^*) is injective (ker = im at $\textcircled{1}$) so we say the seq. is exact at $\textcircled{1}$

2. $\ker(\partial_V^* - \partial_U^*) = \text{im}(\iota_U^*, \iota_V^*)$ b/c if they agree on $U \cap V$ they glue to a form of $U \cup V$. $\Rightarrow$ Exact at $\textcircled{2}$

3. Seq. is exact at $\textcircled{3}$ i.e., $\partial_v^* - \partial_v^*$ is surjective.

Not trivial to show $\rightarrow$ if $\alpha \in \mathcal{Q}^k(U \cap V)$ use P.O.U.

$$\psi_0 + \psi_1 = 1$$

$$\alpha = \underbrace{\psi \alpha}_{\text{well-def. in } U} - \underbrace{(-\psi_U \alpha)}_{\text{well-def. in } V}$$

□

Def: Such a 3-term exact sequence

$$0 \rightarrow (A, d_A) \rightarrow (B, d_B) \rightarrow (C, d_C) \rightarrow 0$$

is called a short exact sequence of complexes.

Upshot: de Rham complexes of M , $U \sqcup V$, $U \cap V$ are related by a short exact sequence.

Thm: Any short exact sequence $0 \rightarrow A^\bullet \xrightarrow{f} B^\bullet \xrightarrow{g} C^\bullet \rightarrow 0$ induces a long exact sequence on $H^*(A), H^*(B), H^*(C)$:

Mayer-Vietoris sequence

layer - value
 sequence

$$\begin{array}{c}
 \dots \rightarrow H^{k+1}(A) \rightarrow H^{k+1}(B) \rightarrow H^{k+1}(C) \rightarrow \dots \\
 \downarrow \\
 \dots \rightarrow H^k(A) \xrightarrow{f_*} H^k(B) \xrightarrow{g_*} H^k(C) \rightarrow \dots \\
 \downarrow \\
 \dots \rightarrow H^{k-1}(A) \xrightarrow{f_*} H^{k-1}(B) \xrightarrow{g_*} H^{k-1}(C) \rightarrow \dots
 \end{array}$$

connecting homomorphism